

# DUAL CHANNEL, 14-BIT, 125/105/80/65 MSPS ADC WITH SERIAL LVDS OUTPUTS

Check for Samples: ADS6245, ADS6244, ADS6243, ADS6242

#### **FEATURES**

- Maximum Sample Rate: 125 MSPS
- 14-Bit Resolution with No Missing Codes
- Simultaneous Sample and Hold
- 3.5 dB Coarse Gain and up to 6 dB Programmable Fine Gain for SFDR/SNR Trade-Off
- Serialized LVDS Outputs with Programmable Internal Termination Option
- Supports Sine, LVCMOS, LVPECL, LVDS Clock Inputs and Amplitude down to 400 mV<sub>pp</sub>
- Internal Reference with External Reference Support
- No External Decoupling Required for References
- 3.3-V Analog and Digital Supply
- 48 QFN Package (7 mm × 7 mm)

- Pin Compatible 12-Bit Family (ADS622X -SLAS543A)
- Feature Compatible Quad Channel Family (ADS644X - SLAS531A and ADS642X -SLAS532A)

#### **APPLICATIONS**

- Base-Station IF Receivers
- Diversity Receivers
- Medical Imaging
- Test Equipment

Table 1. ADS62XX Dual Channel Family

	125 MSPS	105 MSPS	80 MSPS	65 MSPS
<b>ADS624X</b> 14 Bit	ADS6245	ADS6244	ADS6243	ADS6242
<b>ADS622X</b> 12 Bit	ADS6225	ADS6224	ADS6223	ADS6222

**Table 2. Performance Summary** 

		ADS6245	ADS6244	ADS6243	ADS6242
SFDR, dBc	Fin = 10MHz (0 dB gain)	87	91	92	93
SPDK, GBC	Fin = 170MHz (3.5 dB gain)	79	83	84	84
CINAD ADEC	Fin = 10MHz (0 dB gain)	73.4	73.4	74.2	74.3
SINAD, dBFS	Fin = 170MHz (3.5 dB gain)	68.3	69.3	69.4	70
P	ower, per channel, mW	500	405	350	315

#### **DESCRIPTION**

ADS6245/ADS6244/ADS6243/ADS6242 (ADS624X) is a family of high performance 14-bit 125/105/80/65 MSPS dual channel A-D converters. Serial LVDS data outputs reduce the number of interface lines, resulting in a compact 48-pin QFN package (7 mm × 7mm) that allows for high system integration density. The device includes 3.5 dB coarse gain option that can be used to improve SFDR performance with little degradation in SNR. In addition to the coarse gain, fine gain options also exist, programmable in 1dB steps up to 6dB.

The output interface is 2-wire, where each ADC data is serialized and output over two LVDS pairs. This makes it possible to halve the serial data rate (compared to a 1-wire interface) and restrict it to less than 1Gbps easing receiver design. The ADS624X also includes the traditional 1-wire interface that can be used at lower sampling frequencies.

An internal phase lock loop (PLL) multiplies the incoming ADC sampling clock to derive the bit clock. The bit clock is used to serialize the 14-bit data from each channel. In addition to the serial data streams, the frame and bit clocks are also transmitted as LVDS outputs.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





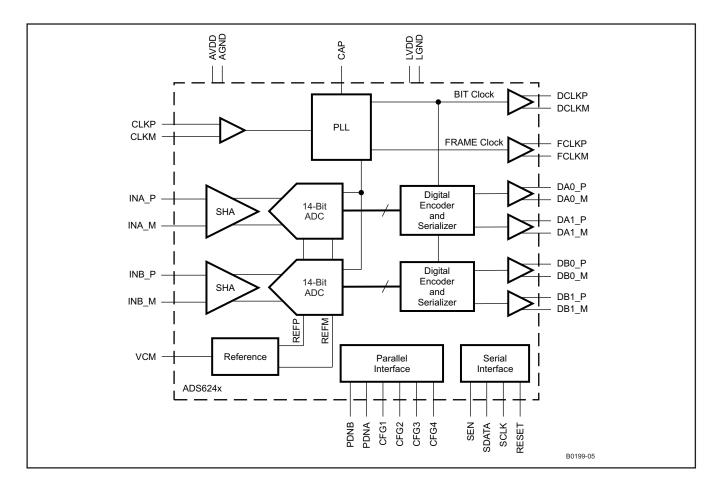
These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# **DESCRIPTION (CONTINUED)**

The LVDS output buffers have features such as programmable LVDS currents, current doubling modes and internal termination options. These can be used to widen eye-openings and improve signal integrity, easing capture by the receiver.

The ADC channel outputs can be transmitted either as MSB or LSB first and 2s complement or straight binary.

ADS624X has internal references, but can also support an external reference mode. The device is specified over the industrial temperature range (–40°C to 85°C).





# PACKAGE/ORDERING INFORMATION(1)

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
ADS6245	QFN-48 <sup>(2)</sup>	RGZ	–40°C to 85°C	AZ6245	ADS6245IRGZT	250, Tape/reel
AD36245	QFN-46\	RGZ	-40°C 10 85°C	AZ6245	ADS6245IRGZR	2500, Tape/reel
ADCC044	QFN-48 <sup>(2)</sup>	RGZ	400C to 050C	A 70044	ADS6244IRGZT	250, Tape/reel
ADS6244	QFN-48 <sup>(-)</sup>	RGZ	–40°C to 85°C	AZ6244	ADS6244IRGZR	2500, Tape/reel
A D C C C A C	QFN-48 <sup>(2)</sup>	RGZ	400C to 050C	A 700 40	ADS6243IRGZT	250, Tape/reel
ADS6243	QFN-48 <sup>(-)</sup>	RGZ	–40°C to 85°C	AZ6243	ADS6243IRGZR	2500, Tape/reel
A D 000 40	QFN-48 <sup>(2)</sup>	507	4000 1- 0500	A 700 40	ADS6242IRGZT	250, Tape/reel
ADS6242	QFN-48 <sup>(-)</sup>	RGZ	–40°C to 85°C	AZ6242	ADS6242IRGZR	2500, Tape/reel

<sup>(1)</sup> For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.

# ABSOLUTE MAXIMUM RATINGS(1)

		VALUE	UNIT
AVDD	Supply voltage range	-0.3 to 3.9	V
LVDD	Supply voltage range	-0.3 to 3.9	V
	Voltage between AGND and DGND	-0.3 to 0.3	V
	Voltage between AVDD to LVDD	-0.3 to 3.3	V
	Voltage applied to external pin, VCM	-0.3 to 2.0	V
	Voltage applied to analog input pins	-0.3V to minimum ( 3.6, AVDD + 0.3V)	V
T <sub>A</sub>	Operating free-air temperature range	-40 to 85	°C
TJ	Operating junction temperature range	125	°C
T <sub>stg</sub>	Storage temperature range	-65 to 150	°C
	Lead temperature 1,6 mm (1/16") from the case for 10 seconds	220	°C

<sup>(1)</sup> Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

<sup>(2)</sup> For thermal pad size on the package, see the mechanical drawings at the end of this data sheet.  $\theta_{JA} = 23.17$  °C/W (0 LFM air flow),  $\theta_{JC} = 22.1$  °C/W when used with 2 oz. copper trace and pad soldered directly to a JEDEC standard four layer 3 in. x 3 in. PCB.



#### RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
SUPPL	IES					
AVDD	Analog supply voltage		3.0	3.3	3.6	V
LVDD	LVDS Buffer supply voltage		3.0	3.3	3.6	V
ANALO	OG INPUTS					
	Differential input voltage range			2		$V_{pp}$
	Input common-mode voltage			1.5 ±0.1		V
	Voltage applied on VCM in external reference mod	le	1.45	1.50	1.55	V
CLOCK	( INPUT					
		ADS6245	5		125	
	lanut deels comple acts. F	ADS6244	5		105	MCDC
	Input clock sample rate, F <sub>s</sub>	ADS6243	5		80	MSPS
		ADS6242	5		65	
		Sine wave, ac-coupled	0.4	1.5		
		LVPECL, ac-coupled		± 0.8		.,
	Input clock amplitude differential ( $V_{CLKP} - V_{CLKM}$ )	LVDS, ac-coupled		± 0.35		$V_{pp}$
		LVCMOS, ac-coupled		3.3		
	Input Clock duty cycle		35%	50%	65%	
DIGITA	AL OUTPUTS					
^	Maximum external load capacitance from each	Without internal termination		5		
$C_{LOAD}$	output pin to DGND	With internal termination		10		pF
R <sub>LOAD</sub>	Differential load resistance (external) between the	LVDS output pairs		100		Ω
T <sub>A</sub>	Operating free-air temperature		-40		85	°C

### **ELECTRICAL CHARACTERISTICS**

	PARAMETER	-	ADS6245 : 125 MSI			DS6244 105 MS		-	ADS6243 = 80 MSF	es	_	ADS6242 = 65 MSF		UNIT
		MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	:
RESOLU	ITION		14			14			14			14		Bits
ANALOG	S INPUT									,				
	Differential input voltage range		2.0			2.0			2.0			2.0		$V_{PP}$
	Differential input capacitance		7			7			7			7		pF
	Analog input bandwidth		500			500			500			500		MHz
	Analog input common mode current (per input pin of each ADC)		155			130			100			81		μА
REFERE	NCE VOLTAGES													
VREFB	Internal reference bottom voltage		1.0			1.0			1.0			1.0		V
VREFT	Internal reference top voltage		2.0			2.0			2.0			2.0		V
$\Delta V_{REF}$	Internal reference error, (VREFT–VREFB)	-15	±2	15	-15	±2	15	-15	±2	15	-15	±2	15	mV
VCM	Common mode output voltage		1.5			1.5			1.5			1.5		V
	VCM output current capability		±4			±4			±4			±4		mA



	PARAMETER	Fs	ADS6245 = 125 MSI	PS		ADS6244 = 105 MS	PS	F,	ADS6243 = 80 MSF	es	F,	ADS6242 = 65 MSP	s	UNIT
		MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
DC ACC	CURACY													
	No missing codes		Assured			Assured			Assured			Assured		
E <sub>O</sub>	Offset error, across devices and across channels within a device	-15	±2	15	-15	±2	15	-15	±2	15	<b>–15</b>	±2	15	mV
	Offset error temperature coefficient, across devices and across channels within a device		0.05			0.05			0.05			0.05		mV/°C
	There are two sources of gain	n error - i	nternal ref	erence i	naccurac	y and cha	annel ga	ain error						
E <sub>GREF</sub>	Gain error due to internal reference inaccuracy alone, $(\Delta V_{REF}/2.0)$ %	-0.75	±0.1	0.75	-0.75	±0.1	0.75	-0.75	±0.1	0.75	-0.75	±0.1	0.75	% FS
	Reference gain error temperature coefficient		0.0125			0.0125			0.0125			0.0125		Δ%/°C
E <sub>GCHAN</sub>	Gain error of channel alone, across devices and across channels within a device (1)	-1	±0.3	1	-1	±0.3	1	-1	±0.3	1	-1	±0.3	1	% FS
	Channel gain error temperature coefficient, across devices and across channels within a device		0.005			0.005			0.005			0.005		Δ%/°C
DNL	Differential nonlinearity	-0.95	±0.6	2.5	-0.9	±0.6	2.5	-0.9	±0.5	2.0	-0.9	±0.5	2.5	LSB
INL	Integral nonlinearity	-5	±3	5	-5	±3	5	-4.5	±2	4.5	-4.5	±2	4.5	LSB
PSRR	DC power supply rejection ratio		0.5			0.5			0.5			0.5		mV/V
POWER	SUPPLY													
I <sub>CC</sub>	Total supply current		300			245			210			190		mA
I <sub>AVDD</sub>	Analog supply current		237			185			155			140		mA
I <sub>LVDD</sub>	LVDS supply current		63	<u>-</u>		60			55	<u>-</u>		50		mA
	Total power		1.0	1.2		0.81	0.97		0.7	0.85		0.63	0.8	W
	Power down (with input clock stopped)		77	150		77	150		77	150		77	150	mW

<sup>(1)</sup> This is specified by design and characterization; it is not tested in production.



#### **ELECTRICAL CHARACTERISTICS**

PARAMETER	TEST C	ONDITIONS		DS6245 125 MS			DS6244 105 MS			DS6243 80 MS			ADS6242 = 65 MSI		UNIT
			MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
DYNAMIC AC	CHARACTERI	STICS													
	Fin = 10 MHz			73.7			73.8			74.4			74.5		
	Fin = 50 MHz		68.5	73.1			73.2		70	73.8		70.5	74		
	Fin = 70 MHz			72.7		69	73			73.4			73.6		
CNID	Fin = 100 MH	Z		72.1			72.2			72.7			72.8		
SNR Signal to	F: 470	0 dB gain		69.9			70.2			70.5			70.7		dBFS
noise ratio	Fin = 170 MHz	3.5 dB Coarse gain		69.4			69.7			69.7			70.2		
	F:- 000	0 dB gain		68.7			68.8			68.1			69.2		
	Fin = 230 MHz	3.5 dB Coarse gain		68.1			68.2			67.7			68.9		
	Fin = 10 MHz	•		73.4			73.4			74.2			74.3		
	Fin = 50 MHz		68	72.3			71.7		69.5	73.5		70	73.7		
	Fin = 70 MHz			71.2		68.5	72			73			73.2		
SINAD	Fin = 100 MH	Z		71.8			72			72.2			72		
Signal to	E: 150	0 dB gain		67.9			69.8			69.9			70.3		dBF
noise and distortion ratio	Fin = 170 MHz	3.5 dB Coarse gain		68.3			69.3			69.4			70		
	F: 000	0 dB gain		67.8			67.7			67.6			68.3		
	Fin = 230 MHz	3.5 dB Coarse gain		67.9			67.6			68.1			68.4		
RMS Output noise	Inputs tied to	common-mode		1.05			1.05			1.05			1.05		LSE
	Fin = 10 MHz			87			91			92			93		
	Fin = 50 MHz		73	81			79		77	87.5		79	88		
	Fin = 70 MHz			78		74	81			86			86		
SFDR	Fin = 100 MH	Z		86			88			84			82		
Spurious free	F: 470	0 dB gain		76			79			80			81		dBo
dynamic range	Fin = 170 MHz	3.5 dB Coarse gain		79			83			84			84		
	F: 000	0 dB gain		77			77			78			79		
	Fin = 230 MHz	3.5 dB Coarse gain		80			80			82			82		
	Fin = 10 MHz			93			94			96			97		
	Fin = 50 MHz		73	87			88		77	90		79	92		
	Fin = 70 MHz			87		74	88			90			92		
LIDO	Fin = 100 MH	<u>z</u>		89			90			87			87		
HD2 Second	E:	0 dB gain		83			84			86			86		dBo
harmonic	Fin = 170 MHz	3.5 dB Coarse gain		85			86			88			88		
	F: 000	0 dB gain		80			81			82			83		
	Fin = 230 MHz	3.5 dB Coarse gain		82			83			84			85		



PARAMETER	TEST C	CONDITIONS		DS6245 125 MS			DS6244 105 MS			DS6243 80 MS			ADS6242 = 65 MSI		UNIT
			MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
	Fin = 10 MHz	:		87			91			92			93		
	Fin = 50 MHz	:	73	81			79		77	87.5		79	88		
	Fin = 70 MHz	:		78		74	81			86			86		
LIDO	Fin = 100 MH	lz		86			88			84			82		
HD3 Third	F:- 470	0 dB gain		76			79			80			81		dBc
harmonic	Fin = 170 MHz	3.5 dB Coarse gain		79			83			84			84		
	F: 000	0 dB gain		77			77			78			79		
	Fin = 230 MHz	3.5 dB Coarse gain		80			80			82			82		
	Fin = 10 MHz	:		91			91			94			95		
Worst	Fin = 50 MHz	:		87			87			92			93		
harmonic (other than	Fin = 100 MH	lz		90			90			91			92		dBc
	Fin = 170 MH	lz		88			88			90			90		
	Fin = 230 MH	lz		87			87			87			87		
	Fin = 10 MHz	:		86			89.5			89			91		
-HD	Fin = 50 MHz		71	78			78.5		75	85.5		77	85.6		
	Fin = 70 MHz			77		72	80			84			84		
harmonic	Fin = 100 MH	lz		84.5			86			83			80.5		dBo
distortion	Fin = 170 MH	lz		73.5			77			78.5			79.5		
	Fin = 230 MH	lz		74			75			76			77		
ENOB	Fin = 50 MHz	:	11.0	11.7					11.1	11.9		11.4	12		
Effective number of bits	Fin = 70 MHz	:				11.3	11.7								Bits
IMD 2-Tone	F1= 46.09 MF F2 = 50.09 M			88			90			96			100		dBFS
intermodulatio n distortion	F1= 185.09 M F2 = 190.09 M			86			88			93			96		UDF
Cross-talk	Near channel Cross-talk sig frequency = 1	ınal		90			92			94			100		dBc
C1055-talk	Far channel Cross-talk sig frequency = 1			103			105			106			108		ивс
Input overload recovery		vithin 1% (of final B overload with out		1			1			1			1		Clock
AC PSRR Power Supply Rejection Ratio	< 100 MHz si AVDD supply	gnal, 100 mV <sub>PP</sub> on		35			35			35			35		dBc



# **DIGITAL CHARACTERISTICS**

The DC specifications refer to the condition where the digital outputs are not switching, but are permanently at a valid logic level 0 or 1 AVDD = LVDD = 3.3V,  $I_O = 3.5$ mA,  $R_{LOAD} = 100\Omega^{(1)}$ .

All LVDS specifications are characterized, but not tested at production.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DIGITAL INPUTS		,			
High-level input voltage		2.4			V
Low-level input voltage				0.8	V
High-level input current			10		μΑ
Low-level input current			10		μΑ
DIGITAL OUTPUTS					
Input capacitance			4		рF
High-level output voltage			1375		mV
Low-level output voltage			1025		mV
Output differential voltage  V <sub>OD</sub>		250	350	450	mV
Output offset voltage V <sub>OS</sub>	Common-mode voltage of OUTP and OUTM		1200		mV
Output capacitance	Output capacitance inside the device, from either output to ground		2		pF

<sup>(1)</sup>  $I_O$  refers to the LVDS buffer current setting,  $R_{LOAD}$  is the external differential load resistance between the LVDS output pair



# TIMING SPECIFICATIONS(1)

Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> clock amplitude,  $C_L = 5$  pF  $^{(2)}$ ,  $I_O = 3.5$  mA,  $R_L = 100$   $\Omega$   $^{(3)}$ , no internal termination, unless otherwise noted.

D.	ADAMETED	TEST	Α	DS624	5		DS624	4	Al	DS6243	3	Α	DS6242	2	LIMIT
Ρ/	ARAMETER	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
tJ	Aperture jitter	Uncertainty in the sampling instant		250			250			250			250		fs rms
Interf	ace: 2-wire, DD	R bit clock, 14x	serializ	ation											
t <sub>su</sub>	Data setup time (4) (5) (6)	From data cross-over to bit clock cross- over	0.35	0.55		0.45	0.65		0.65	0.85		0.8	1.1		ns
t <sub>h</sub>	Data hold time (4) (5) (6)	From bit clock cross-over to data cross- over	0.35	0.58		0.5	0.7		0.7	0.9		0.8	1.1		ns
t <sub>su</sub>	Frame setup time	From frame clock rising edge cross- over to bit clock rising edge cross- over	0.35	0.55		0.45	0.65		0.65	0.85		0.8	1.1		ns
t <sub>h</sub>	Frame hold time	From bit clock falling edge cross-over to frame clock falling edge cross-over	0.35	0.58		0.5	0.7		0.7	0.9		0.8	1.1		ns
t <sub>pd_cl</sub> k	Clock propagation delay <sup>(6)</sup>	Input clock rising edge cross-over to frame clock rising edge cross-over	3.4	4.4	5.4	3.4	4.4	5.4	3.4	4.4	5.4	3.4	4.4	5.4	ns
	Bit clock cycle-cycle jitter <sup>(5)</sup>			350			350			350			350		ps pp
	Frame clock cycle-cycle jitter (5)			75			75			75			75		ps pp
Belov		s apply for 5 MS	PS ≤ Sa	amplin	g freq :	≤ 125 N	ISPS a	nd all in	terface						
t <sub>A</sub>	Aperture delay	Delay from input clock rising edge to the actual sampling instant	1	2	3	1	2	3	1	2	3	1	2	3	ns
	Aperture delay variation	Channel- channel within same device	-250	±80	250	-250	±80	250	-250	±80	250	-250	±80	250	ps

Timing parameters are ensured by design and characterization and not tested in production.

C<sub>L</sub> is the external single-ended load capacitance between each output pin and ground.

 $I_0$  refers to the LVDS buffer current setting;  $R_L$  is the external differential load resistance between the LVDS output pair. Timing parameters are measured at the end of a 2 inch pcb trace (100- $\Omega$  characteristic impedance) terminated by  $R_L$  and  $C_L$ . (4)

Setup and hold time specifications take into account the effect of jitter on the output data and clock.

Refer to Output Timings in application section for timings at lower sampling frequencies and other interface options.



# TIMING SPECIFICATIONS<sup>(1)</sup> (continued)

Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> clock amplitude,  $C_L = 5$  pF  $^{(2)}$ ,  $I_O = 3.5$  mA,  $R_L = 100$   $\Omega$   $^{(3)}$ , no internal termination, unless otherwise noted.

D.4	DAMETED	TEST	Α	DS624	5	,	DS624	4	ΑI	DS6243	}	Α	DS6242	2	LINUT
PA	RAMETER	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
	ADC Latency	Time for a sample to propagate to ADC outputs, see Figure 1		12			12			12			12		Clock cycles
		Time to valid data after coming out of global power down			100			100			100			100	μs
	Wake up time	Time to valid data after input clock is re- started			100			100			100			100	μs
		Time to valid data after coming out of channel standby			200			200			200			200	clock cycles
t <sub>RISE</sub>	Data rise time	From -100 mV to +100 mV	50	100	200	50	100	200	50	100	200	50	100	200	ps
t <sub>FALL</sub>	Data fall time	From +100 mV to -100 mV	50	100	200	50	100	200	50	100	200	50	100	200	ps
t <sub>RISE</sub>	Bit clock and Frame clock rise time	From –100 mV to +100 mV	50	100	200	50	100	200	50	100	200	50	100	200	ps
t <sub>FALL</sub>	Bit clock and Frame clock fall time	From +100 mV to -100 mV	50	100	200	50	100	200	50	100	200	50	100	200	ps
	LVDS Bit clock duty cycle		45%	50%	55%	45%	50%	55%	45%	50%	55%	45%	50%	55%	
	LVDS Frame clock duty cycle		47%	50%	53%	47%	50%	53%	47%	50%	53%	47%	50%	53%	

<sup>(7)</sup> Note that the total latency = ADC latency + internal serializer latency. The serializer latency depends on the interface option selected as listed in Table 28.



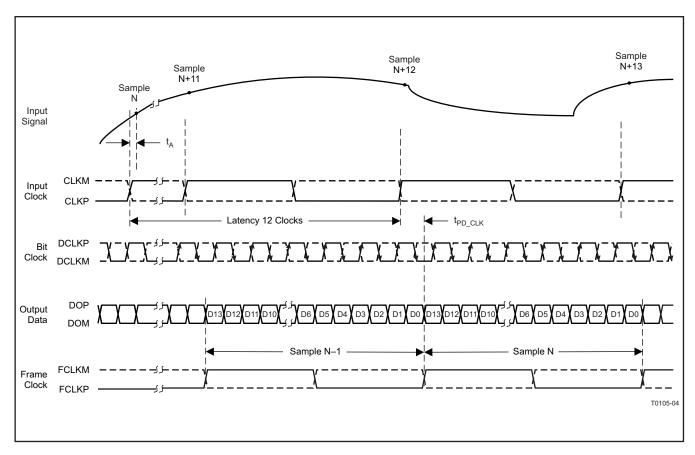


Figure 1. Latency



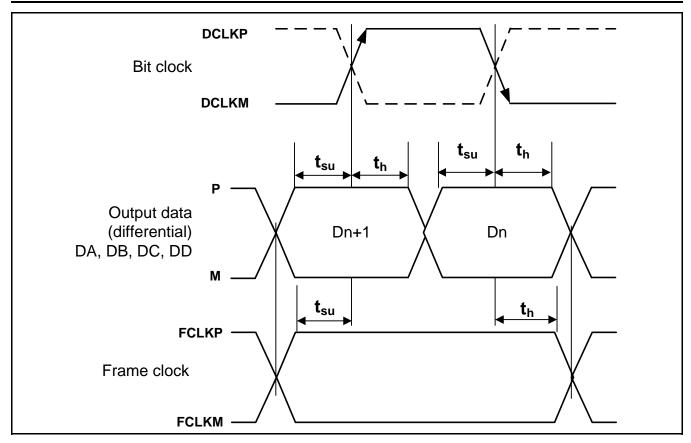


Figure 2. LVDS Timings



#### DEVICE PROGRAMMING MODES

ADS624X offers flexibility with several programmable features that are easily configured.

The device can be configured independently using either parallel interface control or serial interface programming.

In addition, the device supports a third configuration mode, where both the parallel interface and the serial control registers are used. In this mode, the priority between the parallel and serial interfaces is determined by a priority table (Table 4). If this additional level of flexibility is not required, the user can select either the serial interface programming or the parallel interface control.

#### **USING PARALLEL INTERFACE CONTROL ONLY**

To control the device using parallel interface, keep RESET tied to *high* (LVDD). Pins CFG1, CFG2, CFG3, CFG4, PDNA, PDNB, SEN, SCLK, and SDATA are used to directly control certain functions of the ADC. After power-up, the device will automatically get configured as per the parallel pin voltage settings (Table 5 to Table 9) and no reset is required. In this mode, SEN, SCLK, and SDATA function as parallel interface control pins.

Frequently used functions are controlled in this mode—output data interface and format, power down modes, coarse gain and internal/external reference. The parallel pins can be configured using a simple resistor string (with 10% tolerance resistors) as illustrated in Figure 3.

Table 3 has a description of the modes controlled by the parallel pins.

PIN	CONTROL FUNCTIONS
SEN	Coarse gain and internal/external reference.
SCLK, SDATA	Sync, deskew patterns and global power down.
PDNA, PDNB	Dedicated pins for individual channel power down
CFG1	1-wire/2-wire and DDR/SDR bit clock
CFG2	14x/16x serialization and SDR bit clock capture edge
CFG3	Reserved function. Tie CFG3 to Ground.
CFG4	MSB/LSB First and data format.

**Table 3. Parallel Pin Definition** 

#### **USING SERIAL INTERFACE PROGRAMMING ONLY**

In this mode, SEN, SDATA, and SCLK function as serial interface pins and are used to access the internal registers of ADC. The registers must first be reset to their default values either by applying a pulse on RESET pin or by a *high* setting on the <RST> bit (in register). After reset, the RESET pin must be kept **low**.

The serial interface section describes the register programming and register reset in more detail.

Since the parallel pins (CFG1-4, PDNA and PDNB) are not used in this mode, they must be tied to ground. The register override bit <OVRD> - D10 in register 0x0D has to be set *high* to disable the control of parallel interface pins in this serial interface control ONLY mode.

#### **USING BOTH THE SERIAL INTERFACE AND PARALLEL CONTROLS**

For increased flexibility, a combination of serial interface registers and parallel pin controls (CFG1-4, PDNA and PDNB) can also be used to configure the device.

The parallel interface control pins CFG1 to CFG4 and PDNA, PDNB are available. After power-up, the device will automatically get configured as per the parallel pin voltage settings (Table 5 to Table 12) and no reset is required. A simple resistor string can be used as illustrated in Figure 3.

SEN, SDATA, and SCLK function as serial interface pins and are used to access the internal registers of ADC. The registers must first be reset to their default values either by applying a pulse on RESET pin or by a *high* setting on the <RST> bit (in register). After reset, the RESET pin must be kept **low**.

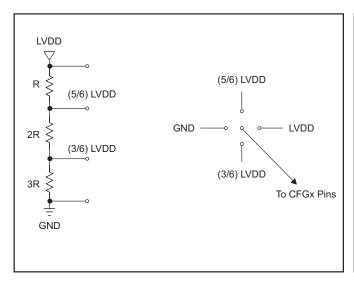
The serial interface section describes the register programming and register reset in more detail.

Since some functions are controlled using both the parallel pins and serial registers, the priority between the two is determined by a priority table (Table 4).



# Table 4. Priority Between Parallel Pins and Serial Registers

PIN	FUNCTIONS SUPPORTED	PRIORITY		
CFG1 to CFG4	As described in	Register bits can control the modes ONLY if the <ovrd> bit is <i>high</i>. If the <ovrd> bit is LOW, then the control voltage on these parallel pins determines the function as per Tables</ovrd></ovrd>		
PDNA	Channel A power down	Channel A power down  D2 bit of register 0x00 controls channel A power down ONLY if PDNA pin is LOW. If PDNA is <b>high</b> , channel A is powered down.		
PDNB	Channel B power down	D3 bit of register 0x00 controls channel B power down ONLY if PDNB pin is LOW. If PDNB is <b>high</b> , channel B is powered down.		
SEN	Serial Interface Enable	COARSE GAIN setting is controlled by bit D5 of register 0X0D ONLY if the <ovrd> bit is <i>high</i>. Else, it is in default register setting of 0 dB COARSE GAIN.</ovrd>		
		INTERNAL/ EXTERNAL Reference setting is determined by bit D6 of register 0x00.		
SCLK,	Serial Interface Clock and	D7, D6, D5 bits of register 0x0A control the SYNC and DESKEW output patterns.		
SDATA	Serial Interface Data pins	Power down is determined by bit D0 of 0x00 register.		



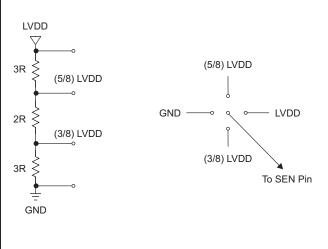


Figure 3. Simple Scheme to Configure Parallel Pins

#### **DESCRIPTION OF PARALLEL PINS**

# Table 5. SCLK, SDATA Control Pins

SCLK	SDATA	DESCRIPTION	
LOW	LOW	NORMAL conversion.	
LOW	HIGH	SYNC - ADC outputs sync pattern on all channels. This pattern can be used by the receiver to align the deserialized data to the frame boundary. See Capture Test Patterns for details.	
HIGH	LOW	POWER DOWN –Global power down, all channels of the ADC are powered down, including internal references, PLL and output buffers.	
HIGH	HIGH	DESKEW - ADC outputs deskew pattern on all channels. This pattern can be used by the receiver to ensure deserializer uses the right clock edge. See Capture Test Patterns for details.	

# **Table 6. SEN Control Pin**

SEN	DESCRIPTION	
0	External reference and 0 dB coarse gain (Full-scale = 2V pp)	
(3/8)LVDD	External reference and 3.5 dB coarse gain (Full-scale = 1.34V pp)	
(5/8)LVDD	Internal reference and 3.5 dB coarse gain (Full-scale = 1.34V pp)	
LVDD	Internal reference and 0 dB coarse gain (Full-scale = 2V pp)	

Submit Documentation Feedback



Independent of the programming mode used, after power-up the parallel pins PDNA, PDNB, CFG1 to CFG4 will automatically configure the device as per the voltage applied (Table 7 to Table 12).

# **Table 7. PDNA Control Pin**

PDNA	DESCRIPTION
0	Normal operation
AVDD	Channel A ADC Power down

#### **Table 8. PDNB Control Pin**

PDNB	DESCRIPTION
0	Normal operation
AVDD	Channel B ADC Power down

# Table 9. CFG1 Control Pin

CFG1	DESCRIPTION
0 (default) + 200mV	DDR bit clock and 1-wire interface
(3/6) LVDD ± 200mV	Not used
(5/6) LVDD ± 200mV	SDR bit clock and 2-wire interface
LVDD - 200mV	DDR bit clock and 2-wire interface

# **Table 10. CFG2 Control Pin**

CFG2	DESCRIPTION
0 (default) + 200mV	14x serialization and capture at falling edge of bit clock (only in 2-wire SDR bit clock mode)
(3/6) LVDD ± 200mV	16x serialization and capture at falling edge of bit clock (only in 2-wire SDR bit clock mode)
(5/6) LVDD ± 200mV	16x serialization and capture at rising edge of bit clock (only in 2-wire SDR bit clock mode)
LVDD - 200mV	14x serialization and capture at rising edge of bit clock (only in 2-wire SDR bit clock mode)

#### Table 11. CFG3 Control Pin

CECO	DECEDVED. TIE TO ODOLIND
CFG3	RESERVED - TIE TO GROUND
0. 00	INECENTED THE TO CHOOMS

#### **Table 12. CFG4 Control Pin**

CFG4	DESCRIPTION
0 (default) + 200mV	MSB First and 2s complement
(3/6) LVDD ± 200mV	MSB First and Offset binary
(5/6) LVDD ± 200mV	LSB First and Offset binary
LVDD - 200mV	LSB First and 2s complement



#### **SERIAL INTERFACE**

The ADC has a serial interface formed by pins SEN (serial interface enable), SCLK (serial interface clock), SDATA (serial interface data) and RESET. Serial shift of bits into the device is enabled when SEN is low. Serial data SDATA is latched at every falling edge of SCLK when SEN is active (low). The serial data is loaded into the register at every 16th SCLK falling edge when SEN is low. In case the word length exceeds a multiple of 16 bits, the excess bits are ignored. Data can be loaded in multiple of 16-bit words within a single active SEN pulse. The interface can work with SCLK frequency from 20 MHz down to very low speeds (few hertz) and even with non-50% duty cycle SCLK.

The first 5-bits of the 16-bit word are the address of the register while the next 11 bits are the register data.

#### **Register Reset**

After power-up, the internal registers *must* be reset to their default values. This can be done in one of two ways:

- 1. Either by applying a high-going pulse on RESET (of width greater than 10ns) **OR**
- 2. By applying software reset. Using the serial interface, set the **<RST>** bit in register 0x00 to *high* this resets the registers to their default values and then self-resets the **<RST>** bit to LOW.

When RESET pin is not used, it must be tied to LOW.

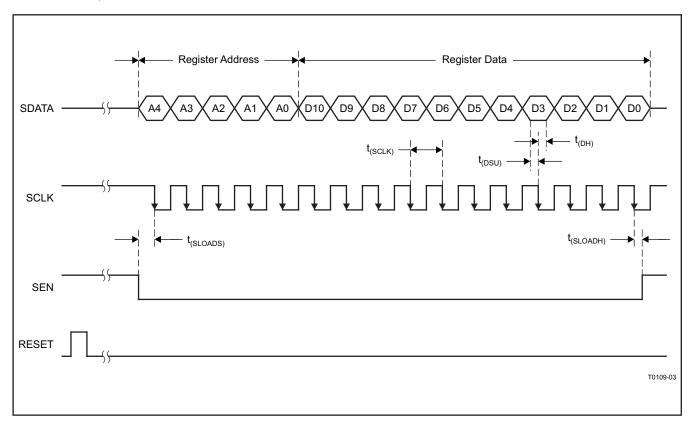


Figure 4. Serial Interface Timing



# **SERIAL INTERFACE TIMING CHARACTERISTICS**

Typical values at 25°C, min and max values across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3V, unless otherwise noted.

	PARAMETER	MIN	TYP	MAX	UNIT
f <sub>SCLK</sub>	SCLK Frequency, f <sub>SCLK</sub> = 1/t <sub>SCLK</sub>	> DC		20	MHz
t <sub>SLOADS</sub>	SEN to SCLK Setup time		25		ns
t <sub>SLOADH</sub>	SCLK to SEN Hold time		25		ns
t <sub>DSU</sub>	SDATA Setup time		25		ns
t <sub>DH</sub>	SDATA Hold time		25		ns
	Time taken for register write to take effect after 16th SCLK falling edge		100		ns

#### **RESET TIMING**

Typical values at 25°C, min and max values across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3V, unless otherwise noted.

	PARMATER	CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>1</sub>	Power-on delay time	Delay from power-up of AVDD and LVDD to RESET pulse active	5			ms
t <sub>2</sub>	Reset pulse width	Pulse width of active RESET signal	10			ns
t <sub>3</sub>	Register write delay time	Delay from RESET disable to SEN active	25			ns
t <sub>PO</sub>	Power-up delay time	Delay from power-up of AVDD and LVDD to output stable		6.5		ms

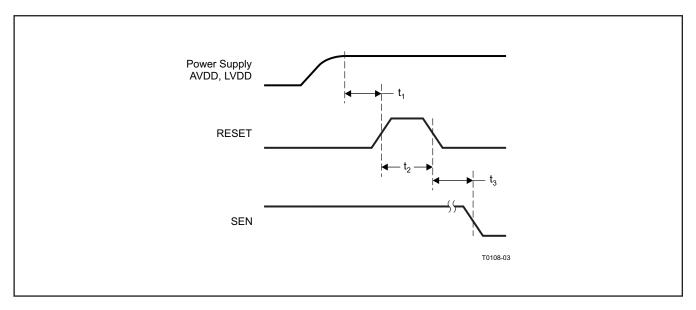


Figure 5. Reset Timing

# NSTRUMENTS

#### **SERIAL REGISTER MAP**

# Table 13. Summary of Functions Supported By Serial Interface

REGISTER ADDRESS					REGIST	ER FUNCTION	S <sup>(1)</sup> (2) (3)				
A4 - A0	D10	D9	D8	D7	D7 D6 D5			D3	D2	D1	D0
00	<rst> S/W RESET</rst>	0	0	0	0	<ref> INTERNAL OR EXTERNAL</ref>	0	<pdn chb=""> POWER DOWN CHB</pdn>	<pdn cha=""> POWER DOWN CH A</pdn>	0	<pdn global=""> GLOBAL POWER DOWN</pdn>
04	0	0	0	0			<b><clkin gain=""></clkin></b> CK BUFFER GA		0	0	
0A	0	<df>DATA FORMAT 2S COMP OR STRAIGHT BINARY</df>	0	Т	<b><patterns></patterns></b> TEST PATTERNS			0	0	0	0
0B					CUSTOM P	<custom a=""> ATTERN (LOW</custom>					
0C	FINE GAIN	<fine gain=""> N CONTROL (10</fine>	dB to 6 dB)	0	0	0	<pre><custom b=""> CUSTOM PATTERN (UPPER 5 BITS)</custom></pre>				
0D	<ovrd> OVERRIDE BIT</ovrd>	0	0	BYTE-WISE OR BIT- WISE	MSB OR LSB FIRST	<coarse gain=""> COURSE GAIN ENABLE</coarse>	FALLING OR RISING BIT CLOCK CAPTURE EDGE	0	14-BIT OR 16-BIT SERIALIZE	DDR OR SDR BIT CLOCK	1-WIRE OR 2-WIRE INTERFACE
10	LVDS	INTERNAL TER	<term clk=""> MINATION BIT</term>	AND WORD CI	LOCKS			CURR> NT SETTINGS			OOUBLE> ENT DOUBLE
11	WORD-WISE CONTROL 0 0 0					0	LV		<term data=""> TERMINATION</term>		JTS

The unused bits in each register (shown by blank cells in above table) must be programmed as 0. Multiple functions in a register can be programmed in a single write operation.

After a hardware or software reset, all register bits are cleared to '0'.



# **DESCRIPTION OF SERIAL REGISTERS**

Note: After a hardware or software reset, all register bits are cleared to '0'.

# Table 14. Serial Register A

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
00	<rst> S/W RESET</rst>	0	0	0	0	<ref> INTERNAL OR EXTERNAL</ref>	0	<pdn chb=""> POWER DOWN CHB</pdn>	<pdn cha=""> POWER DOWN CH A</pdn>	0	<pdn> GLOBAL POWER DOWN</pdn>

D0 - D4	Power down modes
D0	<pdn global=""></pdn>
0	Normal operation
1	Global power down, including all channels ADCs, internal references, internal PLL and output buffers
D2	<pdn a="" ch=""></pdn>
0	CH A powered up
1	CH A ADC powered down
D3	<pdn b="" ch=""></pdn>
0	CH B powered up
1	CH B ADC powered down
D5	<ref> Reference</ref>
0	Internal reference enabled
1	External reference enabled
D10	<rst></rst>
1	Software reset applied – resets all internal registers and self-clears to 0



# Table 15. Serial Register B

REGISTER ADDRESS						вітѕ					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
04	0	0	0	0	<clkin gain=""> INPUT CLOCK BUFFER GAIN CONTROL  0</clkin>				0		

D6 - D2 <CLKIN GAIN> Input clock buffer gain control

11000 Gain 0 Minimum gain 00000 Gain 1, default after reset

Gain 2 01100 01010 Gain 3 Gain 4 01001

01000 Gain 5 Maximum gain

# Table 16. Serial Register C

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0A	0	<df> DATA  DORMAT 2S  COMP OR  STRAIGHT  BINARY</df>	0		<patterns> EST PATTERN</patterns>		0	0	0	0	0

D7 - D5 <pa< th=""><th>TTERNS&gt; Cap</th><th>oture test patterns</th></pa<>	TTERNS> Cap	oture test patterns
--	-------------	---------------------

000 Normal ADC operation 001 Output all zeros

Output all ones 011 Output toggle pattern

100 Unused

010

101 Output custom pattern (contents of CUSTOM pattern registers 0x0B and 0x0C)

110 Output DESKEW pattern (serial stream of 1010..)

111 Output SYNC pattern

D9 <DF> Data format selection

0 2s complement format 1 Straight binary format



# Table 17. Serial Register D

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0B					CUSTOM P	<custom a=""> ATTERN (LOW</custom>					

**D10 - D0 <CUSTOM A>** Lower 11 bits of custom pattern <DATAOUT10>...<DATAOUT0>

# Table 18. Serial Register E

REGISTER ADDRESS						вітѕ					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
0C	<pre><fine gain=""> FINE GAIN CONTROL (1 dB to 6 dB)</fine></pre>			0	0	0		CUSTOM F	<custom b=""></custom>		

**D4 - D0 CUSTOM B>** Upper 5 bits of custom pattern <DATAOUT15>...<DATAOUT11>

D10-D8	<fine gain=""> Fine gain control</fine>
000	0 dB gain (Full-scale range = 2.00 Vpp)
001	1 dB gain (Full-scale range = 1.78 Vpp)
010	2 dB gain (Full-scale range = 1.59 Vpp)
011	3 dB gain (Full-scale range = 1.42 Vpp)
100	4 dB gain (Full-scale range = 1.26 Vpp)
101	5 dB gain (Full-scale range = 1.12 Vpp)
110	6 dB gain (Full-scale range = 1.00 Vpp)

# Table 19. Serial Register F

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
OD	<ovrd> OVER-RIDE BITE</ovrd>	0	0	BYTE-WISE OR BIT- WISE	MSB OR LSB FIRST	<coarse gain=""> COURSE GAIN ENABLE</coarse>	FALLING OR RISING BIT CLOCK CAPTURE EDGE	0	14-BIT OR 16-BIT SERIALIZE	DDR OR SDR BIT CLOCK	1-WIRE OR 2-WIRE INTERFACE

D0	Interface selection
0	1 wire interface
1	2 wire interface
D1	Bit clock selection (only in 2-wire interface)
0	DDR bit clock
1	SDR bit clock
D2	Serialization factor selection
0	14X serialization
1	16X serialization
D4	Bit clock capture edge (only when SDR bit clock is selected, D1=1)
0	Capture data with falling edge of bit clock
1	Capture data with rising edge of bit clock
D5	<coarse gain="">Coarse gain control</coarse>
0	0 dB coarse gain



1	3.5dB coarse gain (Full-scale range = 1.34 Vpp)
D6	MSB or LSB first selection
0	MSB First
1	LSB First
D7	Byte/bit wise outputs (only when 2-wire is selected)
0	Byte wise
1	Bit wise
D10	<b><ovrd></ovrd></b> Over-ride bit. All the functions in register 0x0D can also be controlled using the parallel control pins. By setting bit <ovrd> =1, the contents of register 0x0D will over-ride the settings of the parallel pins.</ovrd>
0	Disable over-ride
1	Enable over-ride

# Table 20. Serial Register G

REGISTER ADDRESS						BITS					
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
10	LVDS	INTERNAL TE	<term clk=""> RMINATION BIT</term>	AND WORD C	LOCKS		<lvds (<br="">LVDS CURREN</lvds>				DOUBLE> RENT DOUBLE
D0	<0	<b>CURR DOUBLE&gt;</b> LVDS current double for data outputs									
0	No	Nominal LVDS current, as set by <d5d2></d5d2>									
1	Do	Double the nominal value									
D1	<0	CURR DOUBLE> LVDS current double for bit and word clock outputs									
0	No	Nominal LVDS current, as set by <d5d2></d5d2>									
1	Do	Double the nominal value									
D3-D2	<l< td=""><td colspan="10"><b>LVDS CURR&gt;</b> LVDS current setting for data outputs</td></l<>	<b>LVDS CURR&gt;</b> LVDS current setting for data outputs									
00	3.	3.5 mA									
01	4 ו	mA									
10	2.	5 mA									
11	3	mA									
D5-D4	<l< th=""><th>VDS CU</th><th>RR&gt; LVD</th><th>S current</th><th>setting fo</th><th>r bit and</th><th>word clock</th><th>outputs</th><th></th><th></th><th></th></l<>	VDS CU	RR> LVD	S current	setting fo	r bit and	word clock	outputs			
00	3.	5 mA									
01	4 1	mA									
10	2.	2.5 mA									
11	3 :	3 mA									



www.ti.com

D10-D6	<term clk=""> LVDS internal termination for bit and word clock outputs</term>
00000	No internal termination
00001	166 Ω
00010	200 Ω
00100	250 Ω
01000	333 Ω
10000	500 Ω
	Any combination of above bits can also be programmed, resulting in a parallel combination of the selected values. For example, 00101 is the parallel combination of $166  250 = 100 \Omega$
00101	100 Ω

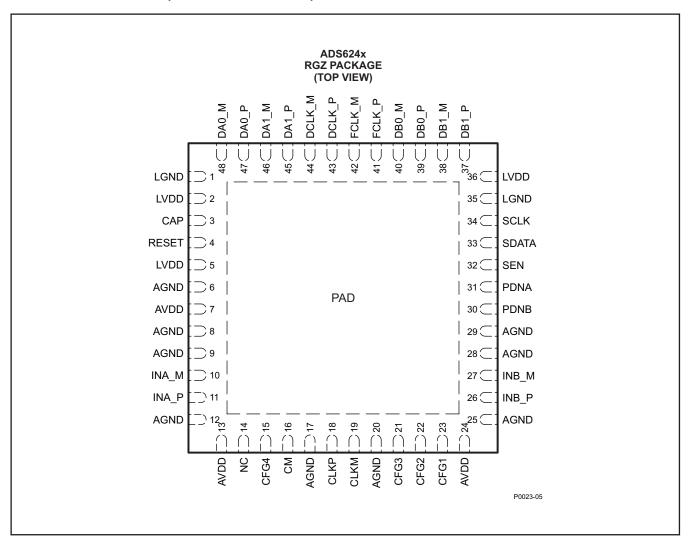
Table 21. Serial Register H

REGISTER ADDRESS		вітѕ									
A4 - A0	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
11	WORD-WISI	WORD-WISE CONTROL		0	0	0	LV		<term data=""> TERMINATION</term>	- DATA OUTPU	ITS

D4-D0	<term data=""> LVDS internal termination for data outputs</term>
00000	No internal termination
00001	166 Ω
00010	200 Ω
00100	250 Ω
01000	333 Ω
10000	500 Ω
	Any combination of above bits can also be programmed, resulting in a parallel combination of the selected values. For example, 00101 is the parallel combination of 166  250 = 100 $\Omega$
00101	100 Ω
D10-D9	Only when 2-wire interface is selected
00	Byte-wise or bit-wise output, 1x frame clock
11	Word-wise output enabled, 0.5x frame clock
01,10	Do not use

# TEXAS INSTRUMENTS

# **PIN CONFIGURATION (2-WIRE INTERFACE)**



#### **PIN ASSIGNMENTS (2-WIRE INTERFACE)**

THE ACCIONMENTO (2 WINE INTERNACE)							
PINS	;		NO.	DESCRIPTION			
NAME	NO.	I/O	OF PINS				
SUPPLY AND GR	SUPPLY AND GROUND PINS						
AVDD	7,13,24		3	Analog power supply			
AGND	6,8,9,12,17, 20,25,28,29		9	Analog ground			
LVDD	2,5,36		3	Digital power supply			
LGND	1,35		2	Digital ground			
INPUT PINS	INPUT PINS						
CLKP, CLKM	18,19	I	2	Differential input clock pair			
INA_P, INA_M	11,10	I	2	Differential input signal pair, channel A. If unused, the pins should be tied to VCM. Do not float.			
INB_P, INB_M	26,27	I	2	Differential input signal pair, channel B. If unused, the pins should be tied to VCM. Do not float.			
CAP	3	ı	1	Connect 2nF capacitor from pin to ground			

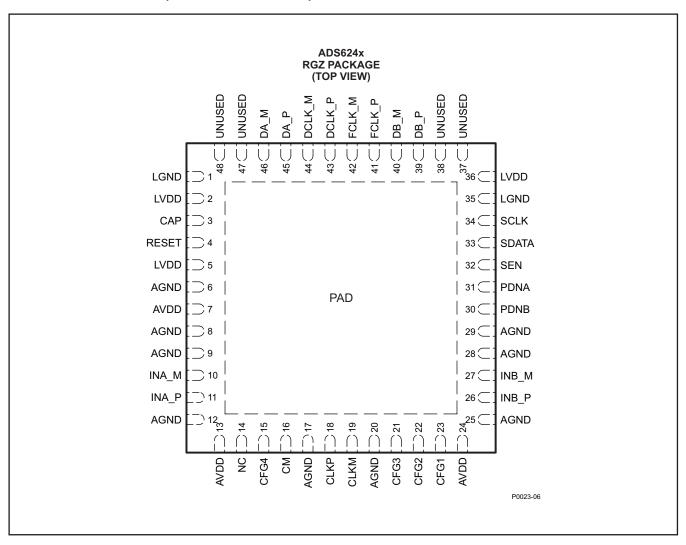


# PIN ASSIGNMENTS (2-WIRE INTERFACE) (continued)

PINS			NO.				
NAME	NO.	I/O	OF PINS	DESCRIPTION			
SCLK	34	I	1	This pin functions as serial interface clock input when RESET is low. When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SDATA). See Table 5 for description. This pin has an internal pull-down resistor.			
SDATA	33	I	1	This pin functions as serial interface data input when RESET is low.  When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SCLK). See Table 5 for description.  This pin has an internal pull-down resistor.			
SEN	32	1	1	This pin functions as serial interface enable input when RESET is low. When RESET is <i>high</i> , it controls coarse gain and internal/external reference modes. See Table 6 for description. This pin has an internal pull-up resistor.			
				Serial interface reset input.			
RESET	4	ı	1	When using the serial interface mode, the user MUST initialize internal registers through hardware RESET by applying a high-going pulse on this pin or by using software reset option. Refer to the Serial Interface section. In parallel interface mode, tie RESET permanently <i>high</i> . (SCLK, SDATA and SEN function as parallel control pins in this mode).			
				The pin has an internal pull-down resistor to ground.			
PDNA	31	I	1	Channel A ADC power down control pin.			
PDNB	30	I	1	Channel B ADC power down control pin.			
CFG1	23	ı	1	Parallel input pin. It controls 1-wire or 2-wire interface and DDR or SDR bit clock selection. See Table 9 for description.  Tie to AVDD for 2-wire interface with DDR bit clock.			
CFG2	22	ı	1	Parallel input pin. It controls 12x or 14x serialization and SDR bit clock capture edge. See Table 10 for description.  For 12x serialization with DDR bit clock, tie to ground or AVDD.			
CFG3	21	I	1	RESERVED pin - Tie to ground.			
CFG4	15	1	1	Parallel input pin. It controls data format and MSB or LSB first modes. See Table 12 for description.			
VCM	16	Ю	1	Internal reference mode – common-mode voltage output External reference mode – reference input. The voltage forced on this pin sets the internal reference.			
OUTPUT PINS		•					
DA0_P,DA0_M	47,48	0	2	Channel A differential LVDS data output pair, wire 0			
DA1_P,DA1_M	45,46	0	2	Channel A differential LVDS data output pair, wire 1			
DB0_P,DB0_M	39,40	0	2	Channel B differential LVDS data output pair, wire 0			
DB1_P,DB1_M	37,38	0	2	Channel B differential LVDS data output pair, wire 1			
DCLKP,DCLKM	43,44	0	2	Differential bit clock output pair			
FCLKP,FCLKM	41,42	0	2	Differential frame clock output pair			
NC	14		1	Do Not Connect			
PAD	0		1	Connect to ground using multiple vias. Refer to Board Design Considerations in application section.			



# PIN CONFIGURATION (1-WIRE INTERFACE)



#### PIN ASSIGNMENTS (1-WIRE INTERFACE)

THE ADDIGNMENTO (1-WINE INTERN ADE)							
PINS		1/0	NO. OF	DECORPTION			
NAME	NO.	1/0	PINS	DESCRIPTION			
SUPPLY AND GROUND PINS							
AVDD	7,13,24		3	Analog power supply			
AGND	6,8,9,12,17, 20,25,28,29		9	Analog ground			
LVDD	2,5,36		3	Digital power supply			
LGND	1,35		2	Digital ground			
INPUT PINS		•	•				
CLKP, CLKM	18,19	I	2	Differential input clock pair			
INA_P, INA_M	11,10	I	2	Differential input signal pair, channel A. If unused, the pins should be tied to VCM. Do not float.			
IND_P, IND_M	26,27	I	12	Differential input signal pair, channel B. If unused, the pins should be tied to VCM. Do not float.			
CAP	3	I	1	Connect 2nF capacitance from pin to ground			



# PIN ASSIGNMENTS (1-WIRE INTERFACE) (continued)

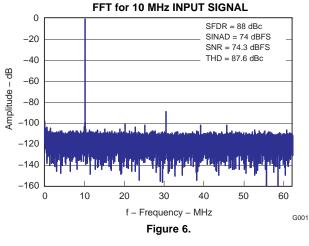
PINS			NO. OF	DECORPORAL			
NAME	NO.	1/0	PINS	DESCRIPTION			
SCLK	34	I	1	This pin functions as serial interface clock input when RESET is <i>low.</i> When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SDATA). See Table 5 for description. This pin has an internal pull-down resistor.			
SDATA	33	1	1	This pin functions as serial interface data input when RESET is <i>low</i> . When RESET is <i>high</i> , it controls DESKEW, SYNC and global POWER DOWN modes (along with SCLK). See Table 5 for description.  This pin has an internal pull-down resistor.			
SEN	32	I	1	This pin functions as serial interface enable input when RESET is <i>low</i> . When RESET is <i>high</i> , it controls coarse gain and internal/external reference modes. See Table 6 for description.  This pin has an internal pull-up resistor.			
RESET	4	I	1	Serial interface reset input.  When using the serial interface mode, the user MUST initialize internal registers through hardware RESET by applying a high-going pulse on this pin or by using software reset option. Refer to the Serial Interface section. In parallel interface mode, tie RESET permanently <i>high</i> . (SCLK, SDATA and SEN function as parallel control pins in this mode).  The pin has an internal pull-down resistor to ground.			
PDNA	31	1	1	Channel A ADC power down control pin.			
PDNB	30	1	1	Channel B ADC power down control pin.			
CFG1	23	ı	1	Parallel input pin. It controls 1-wire or 2-wire interface and DDR or SDR bit clock selection. See Table 9 for description.  Tie to ground for 1-wire interface with DDR bit clock.			
CFG2	22	ı	1	Parallel input pin. It controls 12x or 14x serialization and SDR bit clock capture edge. See Table 10 for description. For 12x serialization with DDR bit clock, tie to ground or AVDD.			
CFG3	21	1	1	RESERVED pin - Tie to ground.			
CFG4	15	ı	1	Parallel input pin. It controls data format and MSB or LSB first modes. See Table 12 for description.			
VCM	16	Ю	1	Internal reference mode – common-mode voltage output  External reference mode – reference input. The voltage forced on this pin sets the internal reference.			
<b>OUTPUT PINS</b>	·						
DA_P,DA_M	45,46	0	2	Channel A differential LVDS data output pair			
DB_P,DB_M	39,40	0	2	Channel B differential LVDS data output pair			
DCLKP,DCLKM	43,44	0	2	Differential bit clock output pair			
FCLKP,FCLKM	41,42	0	2	Differential frame clock output pair			
UNUSED	37,38,47,48		4	These pins are unused in the 1-wire interface. Do not connect			
NC	14		1	Do not connect			
PAD	0		1	Connect to ground using multiple vias. Refer to Board Design Considerations in application section.			

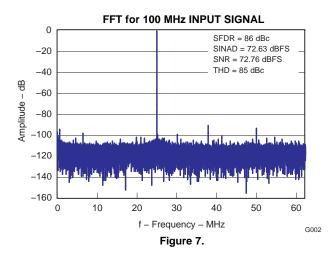


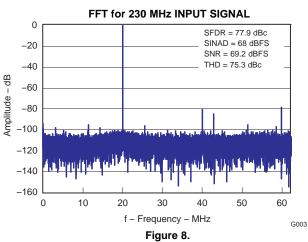
# TYPICAL CHARACTERISTICS

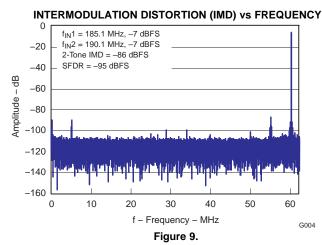
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

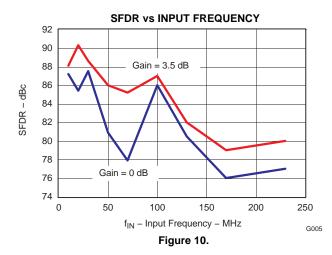
# $ADS6245 (F_s = 125 MSPS)$

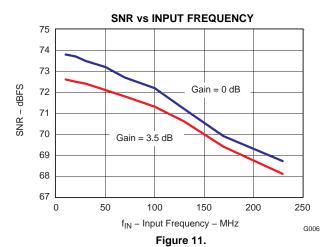














All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

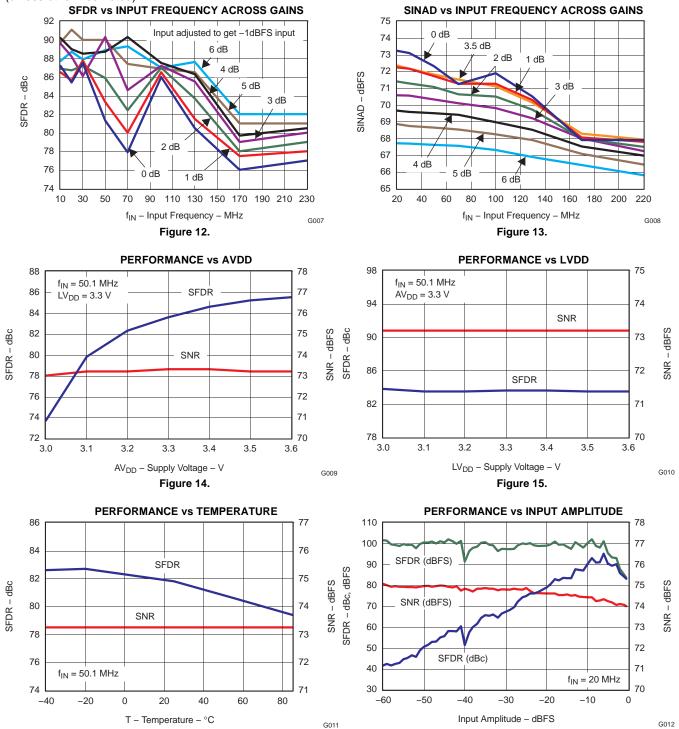
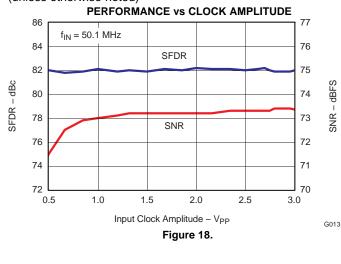


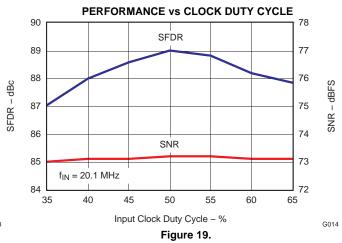
Figure 16.

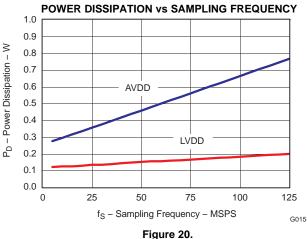
Figure 17.

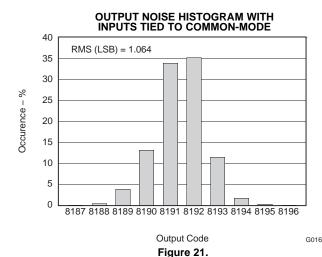


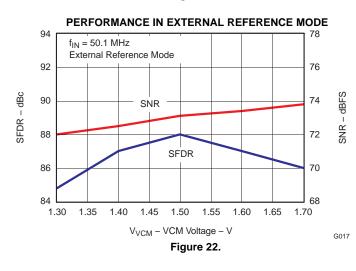
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

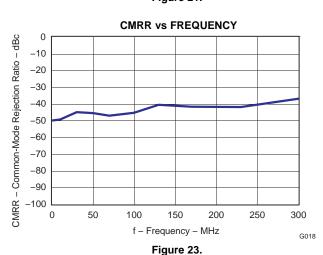








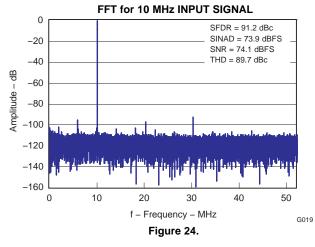


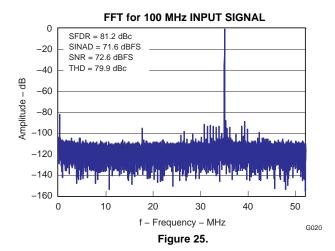


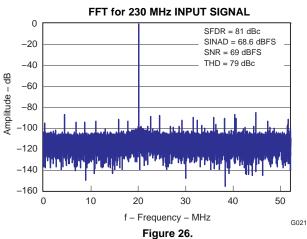


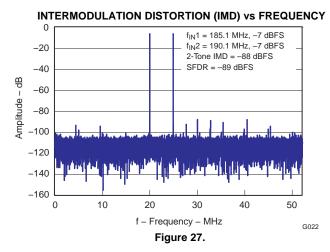
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

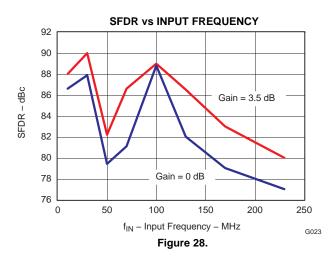
# $ADS6244 (F_s = 105 MSPS)$

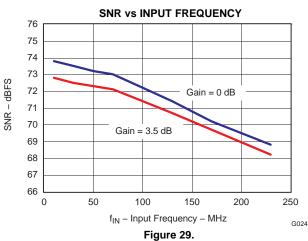






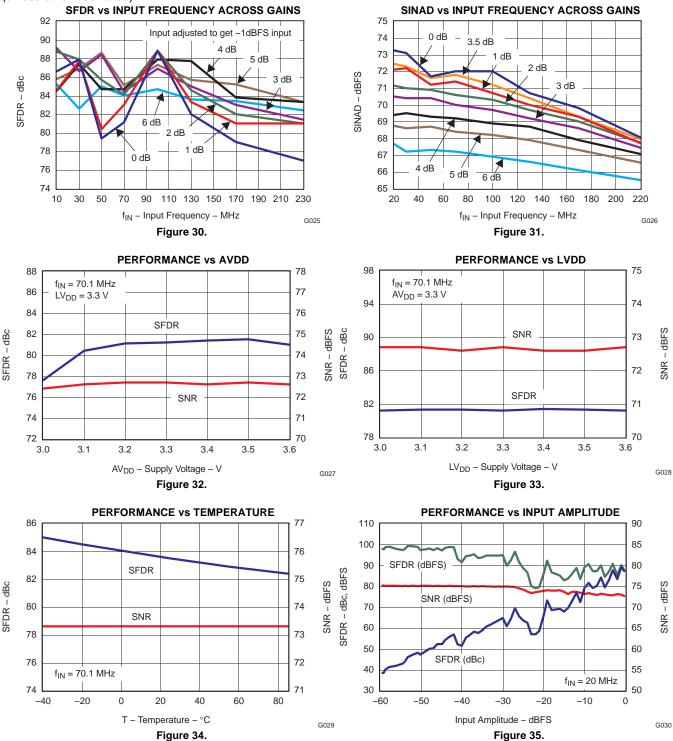






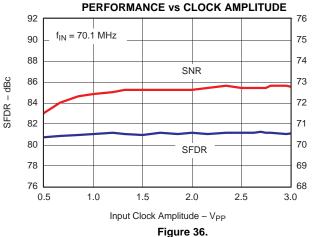


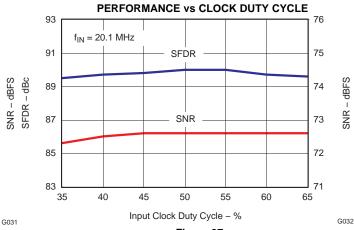
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)



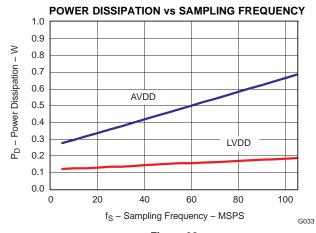


All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)









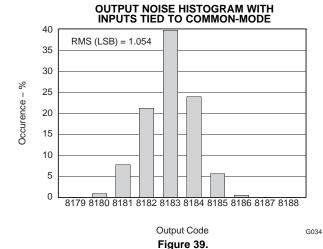
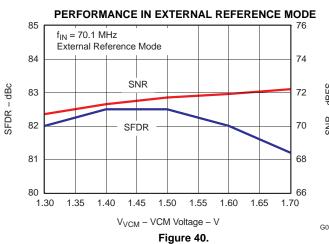
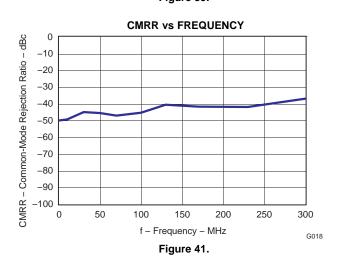


Figure 38.



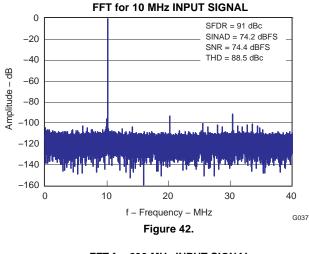


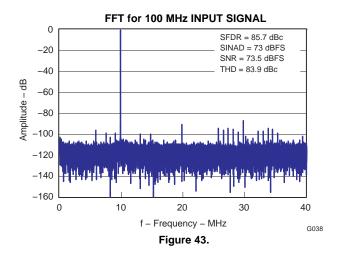
Copyright © 2007–2013, Texas Instruments Incorporated

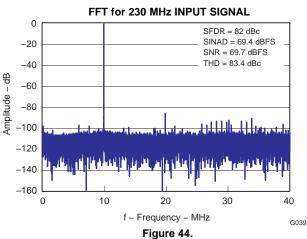


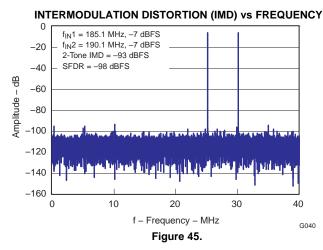
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

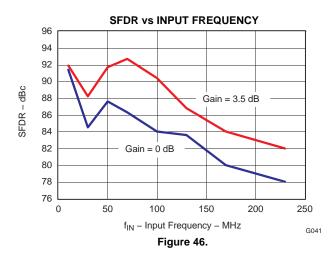
# $ADS6243 (F_s = 80 MSPS)$

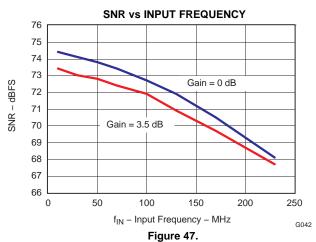














All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

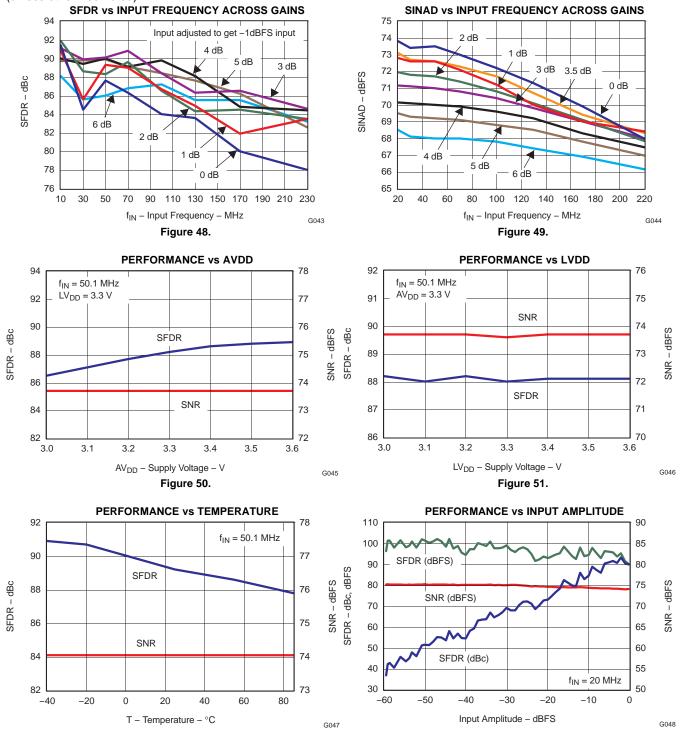
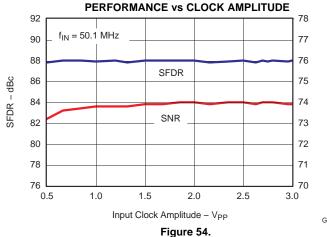


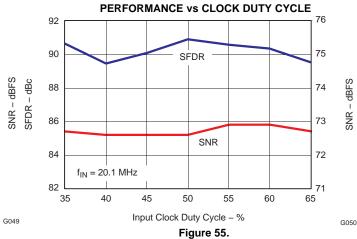
Figure 52.

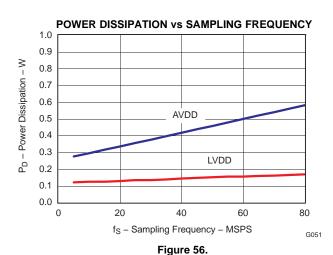
Figure 53.

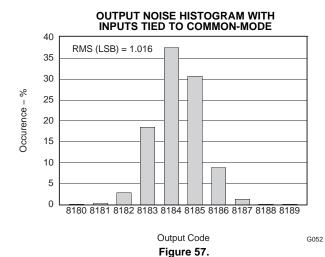


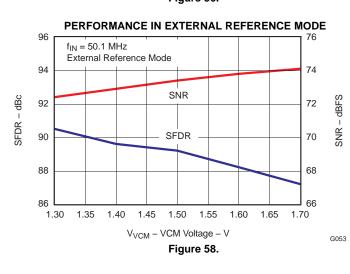
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

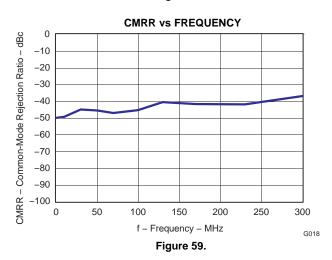








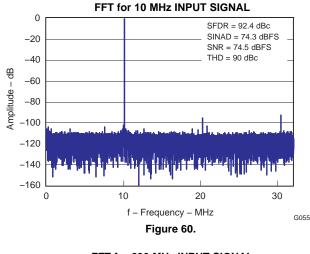


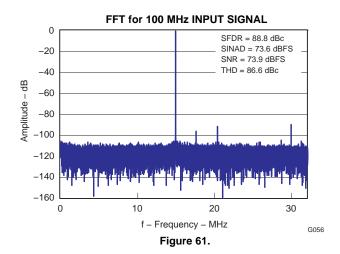


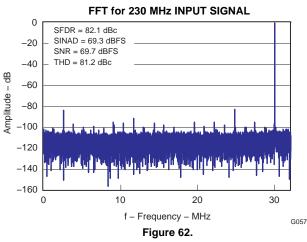


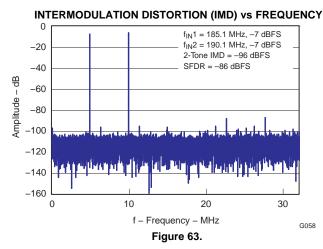
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

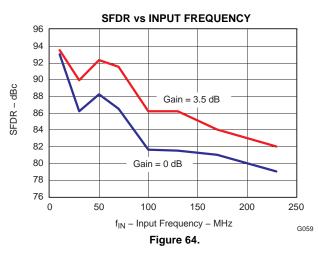
## ADS6242 ( $F_s = 65 MSPS$ )

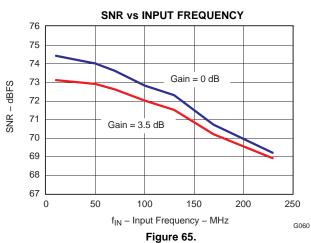






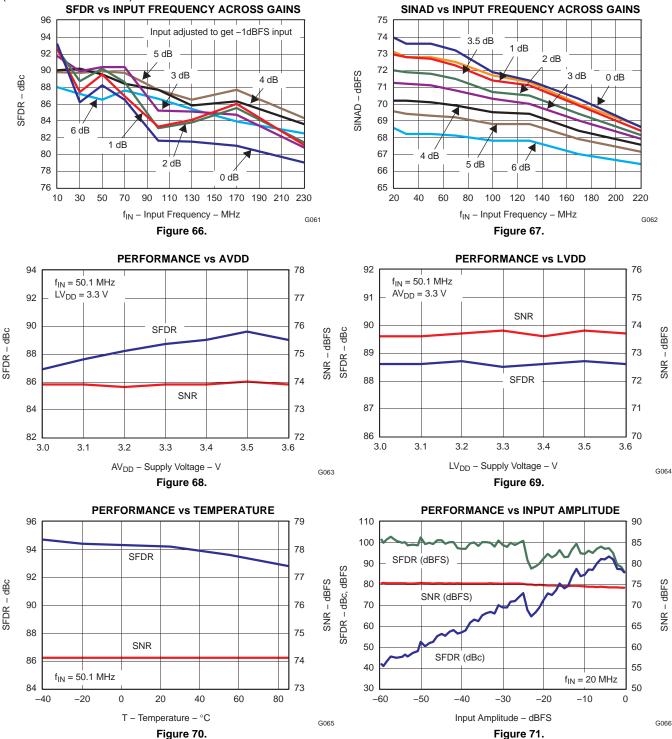






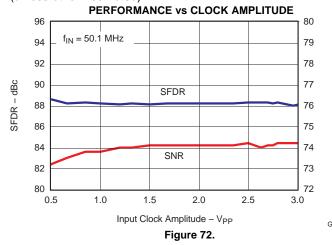


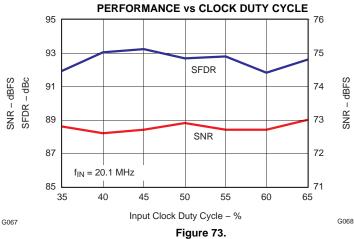
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

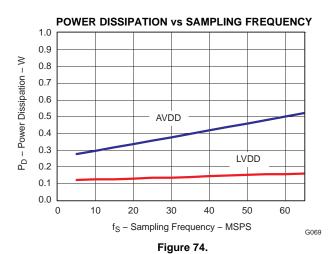


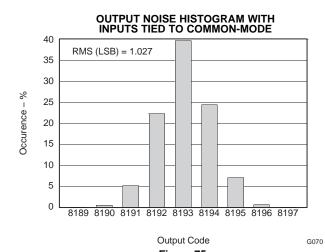


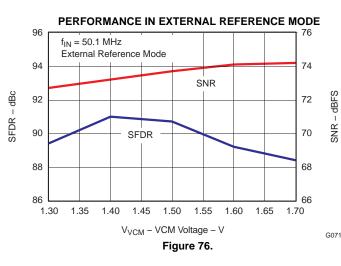
All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

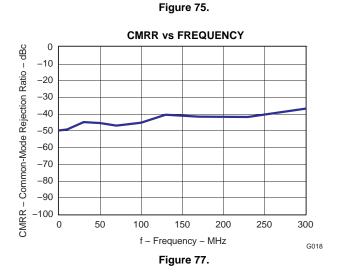














All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

## **Contour Plots across Input and Sampling Frequencies**

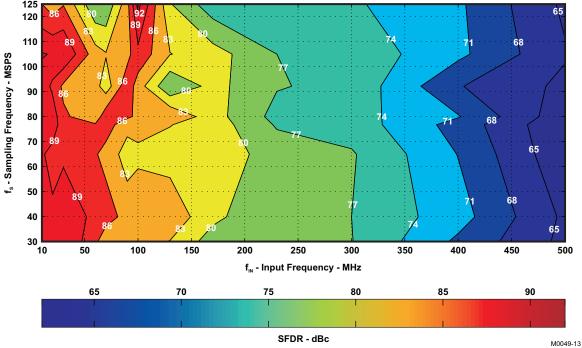


Figure 78. SFDR Contour (no gain)

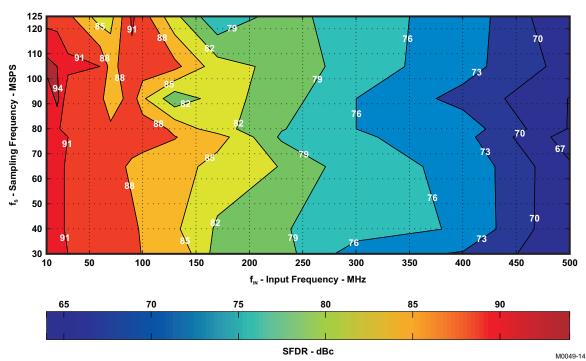


Figure 79. SFDR Contour (3.5 dB coarse gain)



All plots are at 25°C, AVDD = LVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock,  $1.5 \text{ V}_{PP}$  differential clock amplitude, 50% clock duty cycle, -1 dBFS differential analog input, internal reference mode, 0 dB gain 32K point FFT (unless otherwise noted)

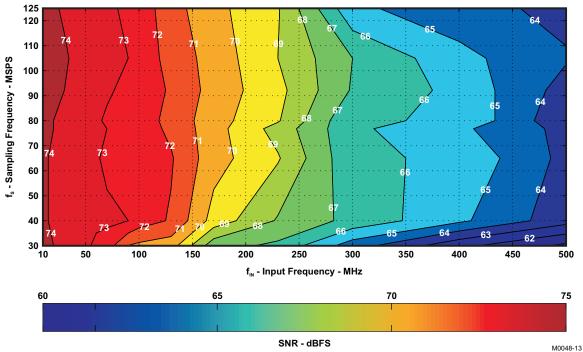


Figure 80. SNR Contour (no gain)

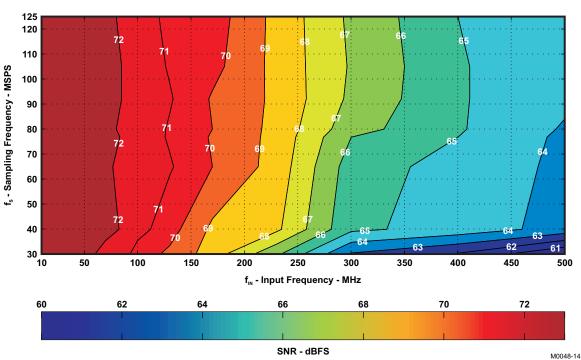


Figure 81. SNR Contour (3.5 dB coarse gain)



#### APPLICATION INFORMATION

#### THEORY OF OPERATION

The ADS6245/ADS6244/ADS6243 (ADS624X) is a family of dual channel, 14-bit pipeline ADC based on switched capacitor architecture in CMOS technology.

The conversion is initiated simultaneously by all the four channels at the rising edge of the external input clock. After the input signals are captured by the sample and hold circuit of each channel, the samples are sequentially converted by a series of low resolution stages. The stage outputs are combined in a digital correction logic block to form the final 14-bit word with a latency of 12 clock cycles. The 14-bit word of each channel is serialized and output as LVDS levels. In addition to the data streams, a bit clock and frame clock are also output. The frame clock is aligned with the 14-bit word boundary.

#### **ANALOG INPUT**

The analog input consists of a switched-capacitor based differential sample and hold architecture, shown in Figure 82. This differential topology results in very good AC performance even for high input frequencies. The INP and INM pins have to be externally biased around a common-mode voltage of 1.5 V, available on VCM pin 13. For a full-scale differential input, each input pin INP, INM has to swing symmetrically between VCM + 0.5 V and VCM – 0.5 V, resulting in a 2- $V_{pp}$  differential input swing. The maximum swing is determined by the internal reference voltages REFP (2.0V nominal) and REFM (1.0 V, nominal). The sampling circuit has a 3 dB bandwidth that extends up to 500 MHz (Figure 83, shown by the transfer function from the analog input pins to the voltage across the sampling capacitors, TF\_ADC).

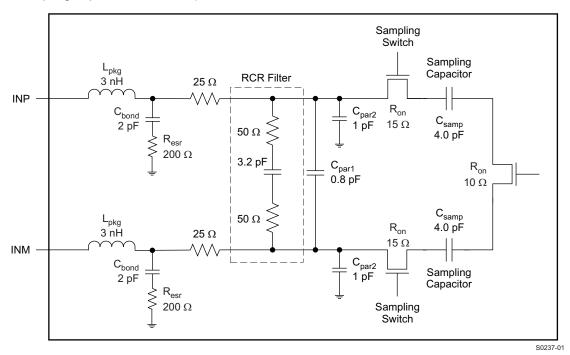


Figure 82. Input Sampling Circuit



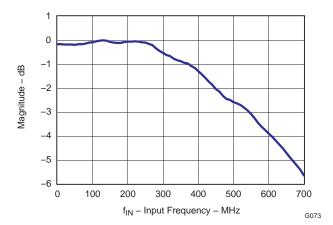


Figure 83. Analog Input Bandwidth (represented by magnitude of TF\_ADC, see Figure 85)

#### **Drive Circuit Requirements**

For optimum performance, the analog inputs must be driven differentially. This improves the common-mode noise immunity and even order harmonic rejection.

A 5- $\Omega$  resistor in series with each input pin is recommended to damp out ringing caused by the package parasitics. It is also necessary to present low impedance (< 50  $\Omega$ ) for the common mode switching currents. For example, this is achieved by using two resistors from each input terminated to the common mode voltage (VCM).

In addition to the above, the drive circuit may have to be designed to provide a low insertion loss over the desired frequency range and matched impedance to the source. While doing this, the ADC input impedance has to be taken into account. Figure 84 shows that the impedance (Zin, looking into the ADC input pins) decreases at high input frequencies. The smith chart shows that the input impedance is capacitive and can be approximated by a series R-C upto 500 MHz.



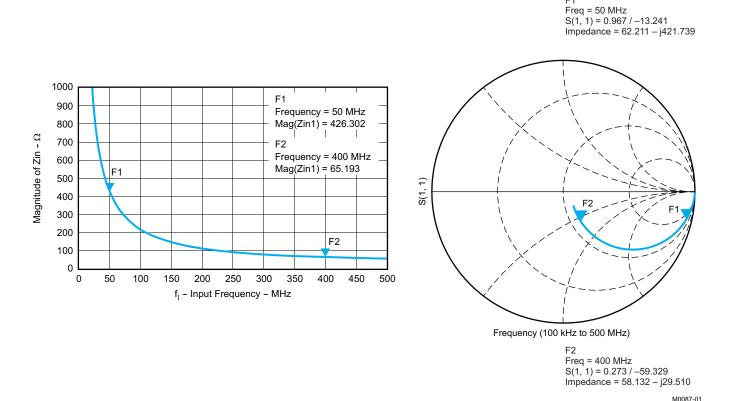


Figure 84. ADC Input Impedance, Zin

## **Using RF-Transformer Based Drive Circuits**

Figure 85 shows a configuration using a single 1:1 turns ratio transformer (for example, Coilcraft WBC1-1) that can be used for low input frequencies (about 100MHz).

The single-ended signal is fed to the primary winding of the RF transformer. The transformer is terminated on the secondary side. Putting the termination on the secondary side helps to shield the kickbacks caused by the sampling circuit from the RF transformer's leakage inductances. The termination is accomplished by two resistors connected in series, with the center point connected to the 1.5 V common mode (VCM pin). The value of the termination resistors (connected to common mode) has to be low (< 100  $\Omega$ ) to provide a low-impedance path for the ADC common-mode switching current.



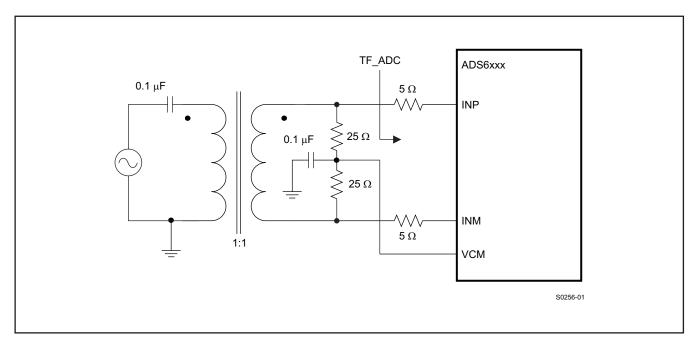


Figure 85. Single Transformer Drive Circuit

At high input frequencies, the mismatch in the transformer parasitic capacitance (between the windings) results in degraded even-order harmonic performance. Connecting two identical RF transformers back-to-back helps minimize this mismatch, and good performance is obtained for high frequency input signals. Figure 86 shows an example using two transformers (Coilcraft WBC1-1). An additional termination resistor pair (enclosed within the shaded box in Figure 86) may be required between the two transformers to improve the balance between the P and M sides. The center point of this termination must be connected to ground.

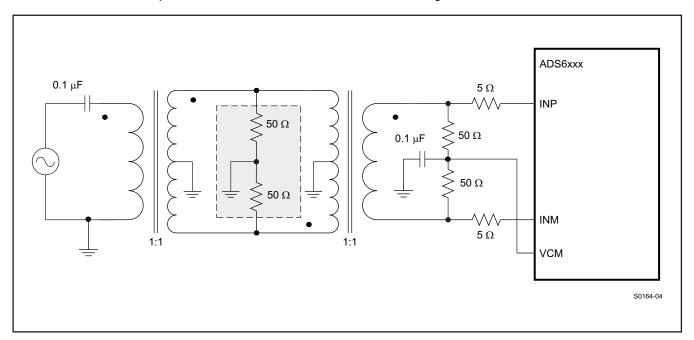


Figure 86. Two Transformer Drive Circuit



#### **Using Differential Amplifier Drive Circuits**

Figure 87 shows a drive ciruit using a differential amplifier (TI's THS4509) to convert a single-ended input to differential output that can be interfaced to the ADC input pins. In addition to the single-ended to differential conversion, the amplifier also provides gain (10dB in Figure 87). As shown in the figure,  $R_{IN}$  helps to isolate the amplifier output from the switching inputs of the ADC. Together with  $C_{IN}$ , it also forms a low-pass filter that bandlimits the noise (and signal) at the ADC input. As the amplifier outputs are ac-coupled, the common-mode voltage of the ADC input spins is set using two resistors connected to VCM.

The amplifier outputs can also be dc-coupled. Using the output common-mode control of the THS4509, the ADC input pins can be biased to 1.5V. In this case, use +4 V and -1 V supplies for the THS4509 to ensure its output common-mode voltage (1.5V) is at mid-supply.

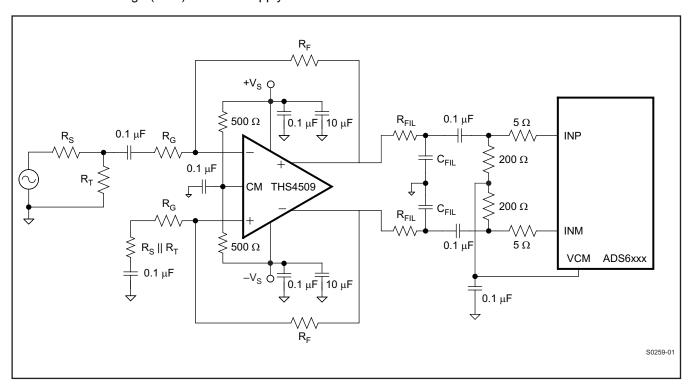


Figure 87. Drive Circuit using THS4509

Refer to the EVM User Guide (SLAU196) for more information.

#### **INPUT COMMON MODE**

To ensure a low-noise common-mode reference, the VCM pin is filtered with a 0.1-µF low-inductance capacitor connected to ground. The VCM pin is designed to directly drive the ADC inputs. The input stage of the ADC sinks a common-mode current in the order of 155 µA at 125 MSPS (per input pin). Equation 1 describes the dependency of the common-mode current and the sampling frequency.

$$\frac{155 \,\mu\text{AxFs}}{125 \,\text{MSPS}} \tag{1}$$

This equation helps to design the output capability and impedance of the CM driving circuit accordingly.

#### **REFERENCE**

The ADS624X has built-in internal references REFP and REFM, requiring no external components. Design schemes are used to linearize the converter load seen by the references; this and the on-chip integration of the requisite reference capacitors eliminates the need for external decoupling. The full-scale input range of the converter can be controlled in the external reference mode as explained below. The internal or external reference modes can be selected by programming the register bit **<REF>** (Table 14).



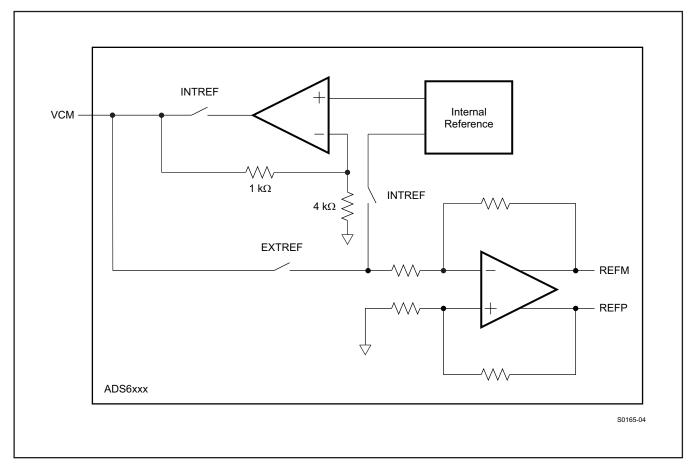


Figure 88. Reference Section

#### Internal Reference

When the device is in internal reference mode, the REFP and REFM voltages are generated internally. Common-mode voltage (1.5 V nominal) is output on VCM pin, which can be used to externally bias the analog input pins.

#### **External Reference**

When the device is in external reference mode, the VCM acts as a reference input pin. The voltage forced on the VCM pin is buffered and gained by 1.33 internally, generating the REFP and REFM voltages. The differential input voltage corresponding to full-scale is given by Equation 2.

Full-scale differential input pp = (Voltage forced on VCM) 
$$\times$$
 1.33

In this mode, the range of voltage applied on VCM should be 1.45 V to 1.55 V. The 1.5-V common-mode voltage to bias the input pins has to be generated externally.

#### **COARSE GAIN AND PROGRAMMABLE FINE GAIN**

ADS624X includes gain settings that can be used to get improved SFDR performance (compared to 0 dB gain mode). The gain settings are 3.5 dB coarse gain and programmable fine gain from 0 dB to 6 dB. For each gain setting, the analog input full-scale range scales proportionally, as shown in Table 22.

The coarse gain is a fixed setting of 3.5 dB and is designed to improve SFDR with little degradation in SNR. The fine gain is programmable in 1 dB steps from 0 to 6 dB. With fine gain also, SFDR improvement is achieved, but at the expense of SNR (there is about 1dB SNR degradation for every 1dB of fine gain).

(2)



So, the fine gain can be used to trade-off between SFDR and SNR. The coarse gain makes it possible to get best SFDR but without losing SNR significantly. At high input frequencies, the gains are especially useful as the SFDR improvement is significant with marginal degradation in SINAD.

The gains can be programmed using the register bits **<COARSE GAIN>** (Table 19) and **<FINE GAIN>** (Table 18). Note that the default gain after reset is 0 dB.

**Table 22. Full-Scale Range Across Gains** 

GAIN, dB	TYPE	FULL-SCALE, V <sub>pp</sub>
0	Default (after reset)	2
3.5	Coarse setting (fixed)	1.34
1		1.78
2		1.59
3	Fig. a catting (and an arrange)	1.42
4	Fine setting (programmable)	1.26
5		1.12
6		1.00

#### **CLOCK INPUT**

The ADS624X clock inputs can be driven differentially (SINE, LVPECL or LVDS) or single-ended (LVCMOS), with little or no difference in performance between them. The common-mode voltage of the clock inputs is set to VCM using internal 5-k $\Omega$  resistors as shown in Figure 89. This allows using transformer-coupled drive circuits for sine wave clock or ac-coupling for LVPECL, LVDS clock sources (see Figure 91 and Figure 93). Figure 90 shows the impedance looking into the clock input pins of the device.



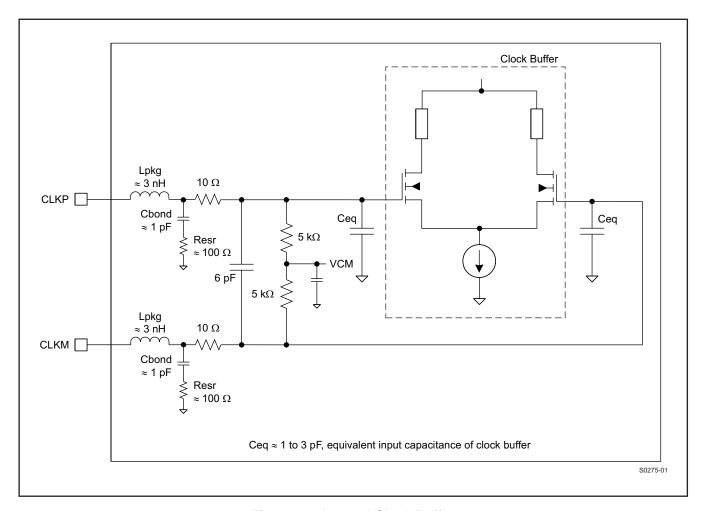


Figure 89. Internal Clock Buffer

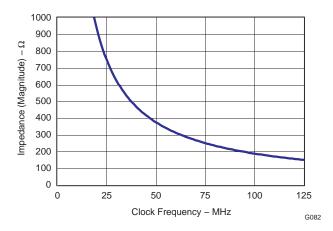


Figure 90. Clock Buffer Input Impedance

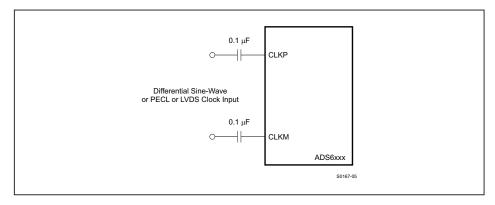


Figure 91. Differential Clock Driving Circuit

Figure 92 shows a typical scheme using PECL clock drive from a CDCM7005 clock driver. SNR performance with this scheme is comparable with that of a low jitter sine wave clock source.

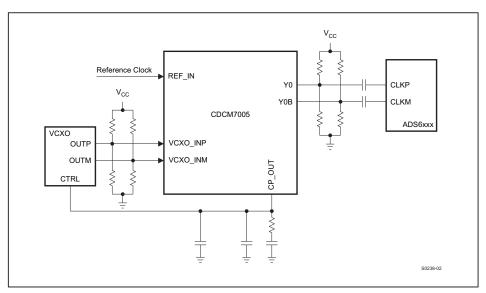


Figure 92. PECL Clock Drive Using CDCM7005

Single-ended CMOS clock can be ac-coupled to the CLKP input, with CLKM (pin) connected to ground with a 0.1-µF capacitor, as shown in Figure 93.

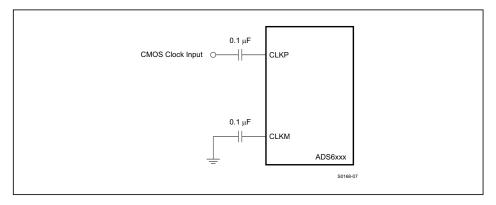


Figure 93. Single-Ended Clock Driving Circuit



For best performance, the clock inputs have to be driven differentially, reducing susceptibility to common-mode noise. For high input frequency sampling, it is recommended to use a clock source with very low jitter. Bandpass filtering of the clock source can help reduce the effect of jitter. There is no change in performance with a non-50% duty cycle clock input.

#### **CLOCK BUFFER GAIN**

When using a sinusoidal clock input, the noise contributed by clock jitter improves as the clock amplitude is increased. Hence, it is recommended to use large clock amplitude. Use clock amplitude greater than 1V pp to avoid performance degradation.

In addition, the clock buffer has programmable gain to amplify the input clock to support very low clock amplitude. The gain can be set by programming the register bits **<CLKIN GAIN>** (Table 15) and increases monotonically from Gain 0 to Gain 5 settings. Table 23 shows the minimum clock amplitude supported for each gain setting.

 CLOCK BUFFER GAIN
 MINIMUM CLOCK AMPLITUDE SUPPORTED, mV pp differential

 Gain 0 (Minimum gain)
 800

 Gain 1 (default gain)
 400

 Gain 2
 300

 Gain 3
 200

 Gain 4
 150

 Gain 5 (Highest gain)
 100

Table 23. Minimum Clock Amplitude across gains

### **POWER DOWN MODES**

The ADS624X has three power down modes – global power down, channel standby and input clock stop.

#### **Global Power Down**

This is a global power down mode in which almost the entire chip is powered down, including the four ADCs, internal references, PLL and LVDS buffers. As a result, the total power dissipation falls to about 77 mW typical (with input clock running). This mode can be initiated by setting the register bit **<PDN GLOBAL>** (Table 14). The output data and clock buffers are in high impedance state.

The wake-up time from this mode to data becoming valid in normal mode is 100 µs.

#### **Channel Standby**

In this mode, only the ADC of each channel is powered down and this helps to get very fast wake-up times. Each of the four ADCs can be powered down independently using the register bits **PDN CH>** (Table 14). The output LVDS buffers remain powered up.

The wake-up time from this mode to data becoming valid in normal mode is 200 clock cycles.

#### **Input Clock Stop**

The converter enters this mode:

- If the input clock frequency falls below 1 MSPS or
- If the input clock amplitude is less than 400 mV (pp, differential with default clock buffer gain setting) at any sampling frequency.

All ADCs and LVDS buffers are powered down and the power dissipation is about 235 mW. The wake-up time from this mode to data becoming valid in normal mode is  $100 \mu s$ .



## Table 24. Power Down Modes Summary (1)

POWER DOWN MODE	AVDD POWER (mW)	LVDD POWER (mW)	WAKE UP TIME
In power-up	782	208	_
Global power down	65	12	100 µs
1 Channel in standby	510	208	200 Clocks
2 Channels in standby	235	208	200 Clocks
Input clock stop	200	35	100 µs

<sup>(1)</sup> Sampling frequency = 125 MSPS.

## **POWER SUPPLY SEQUENCING**

During power-up, the AVDD and LVDD supplies can come up in any sequence. The two supplies are separated inside the device. Externally, they can be driven from separate supplies or from a single supply.



#### **DIGITAL OUTPUT INTERFACE**

The ADS624X offers several flexible output options making it easy to interface to an ASIC or an FPGA. Each of these options can be easily programmed using either parallel pins or the serial interface.

The output interface options are:

- 1-wire, 1x frame clock, 14x and 16x serialization with DDR bit clock
- 2-wire, 1x frame clock, 16x serialization, with DDR and SDR bit clock, byte wise/bit wise/word wise
- 2-wire, 1x frame clock, 14x serialization, with SDR bit clock, byte wise/bit wise/word wise
- 2-wire, (0.5 x) frame clock, 14x serialization, with DDR bit clock, byte wise/bit wise/word wise.

The maximum sampling frequency, bit clock frequency and output data rate will vary depending on the interface options selected (refer to Table 12).

Table 25. Maximum Recommended Sampling Frequency for Different Output Interface Options

	INTERFACE	OPTIONS	MAXIMUM RECOMMENDED SAMPLING FREQUENCY, MSPS	BIT CLOCK FREQUENCY, MHZ	FRAME CLOCK FREQUENCY, MHZ	SERIAL DATA RATE, Mbps	
1-Wire	DDR Bit	14× Serialization	65	455	65	910	
1-11116	clock	16× Serialization	65	520	65	1040	
2-Wire	DDR Bit	14× Serialization	125	437.5	62.5	875	
2-vviie	clock	16× Serialization	125	500	125	1000	
2 Miro	SDR Bit	DR Bit 14x Serialization 65		455	65	910	
2-Wire	clock	16× Serialization	65	520	65	1040	

Each interface option is described in detail below.

#### 1-WIRE INTERFACE - 14× AND 16× SERIALIZATION WITH DDR BIT CLOCK

Here the device outputs the data of each ADC serially on a single LVDS pair (1-wire). The data is available at the rising and falling edges of the bit clock (DDR bit clock). The ADC outputs a new word at the rising edge of every frame clock, starting with the MSB. Optionally, it can also be programmed to output the LSB first. The data rate is 14 x Sample frequency (14x serialization) and 16 x Sample frequency (16x serialization).



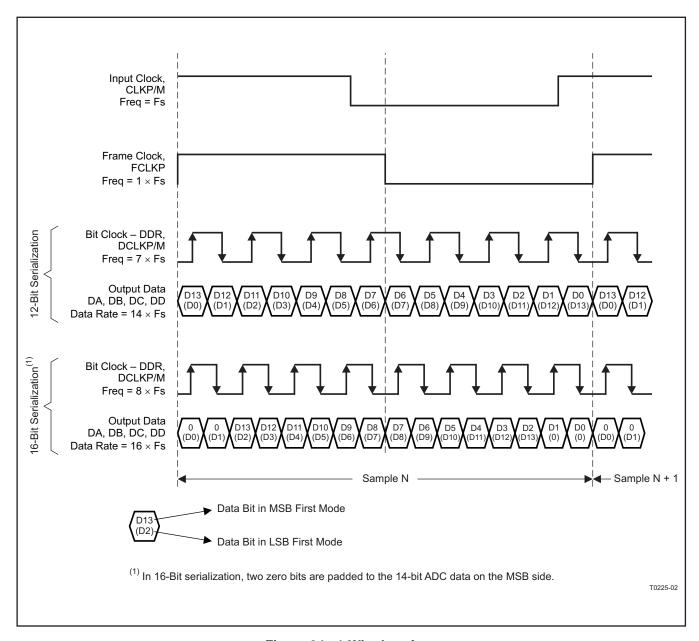


Figure 94. 1-Wire Interface

### 2-WIRE INTERFACE - 16× SERIALIZATION WITH DDR/SDR BIT CLOCK

The 2-wire interface is recommended for sampling frequencies above 65 MSPS. In 16x serialization, two zero bits are padded to the 14-bit ADC data on the MSB side and the combined 16-bit data is serialized and output over two LVDS pairs. The data rate is 8 x Sample frequency since 8 bits are sent on each wire every clock cycle. The data is available along with DDR bit clock or optionally with SDR bit clock. Each ADC sample is sent over the 2 wires as byte-wise or bit-wise or word-wise.

Using the 16x serialization makes it possible to upgrade to a 16-bit ADC in the future seamlessly, without requiring any modification to the receiver capture logic design.



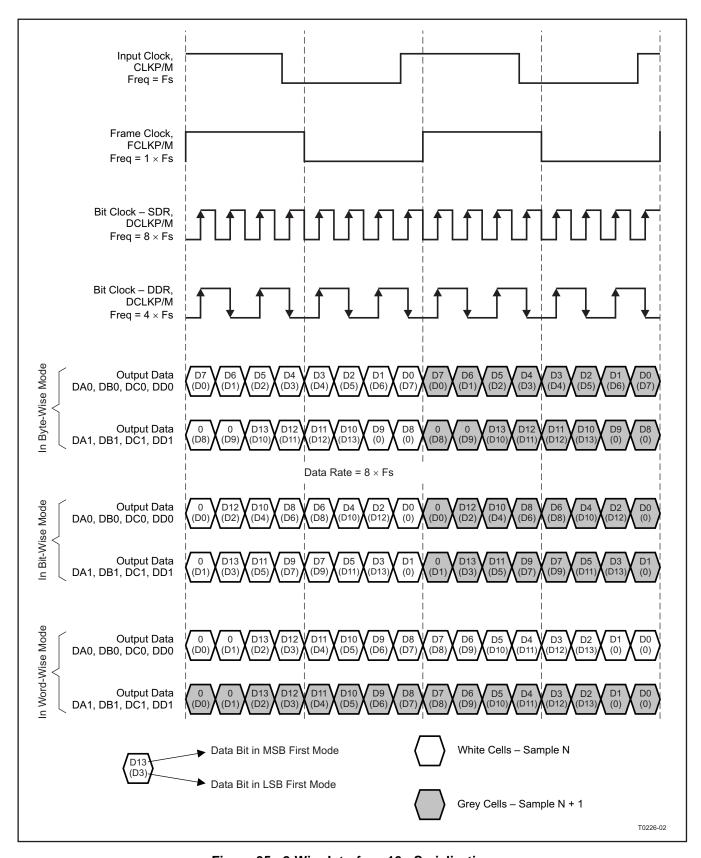


Figure 95. 2-Wire Interface 16× Serialization



#### 2-WIRE INTERFACE - 14× SERIALIZATION

The 14-bit ADC data is serialized and output over two LVDS pairs. A frame clock at 1x sample frequency is also available with an SDR bit clock. With DDR bit clock option, the frame clock frequency is 0.5x sample frequency.

The output data rate will be  $7 \times \text{Sample}$  frequency as 7 data bits are output every clock cycle on each wire. Each ADC sample is sent over the 2 wires as byte-wise or bit-wise or word-wise.



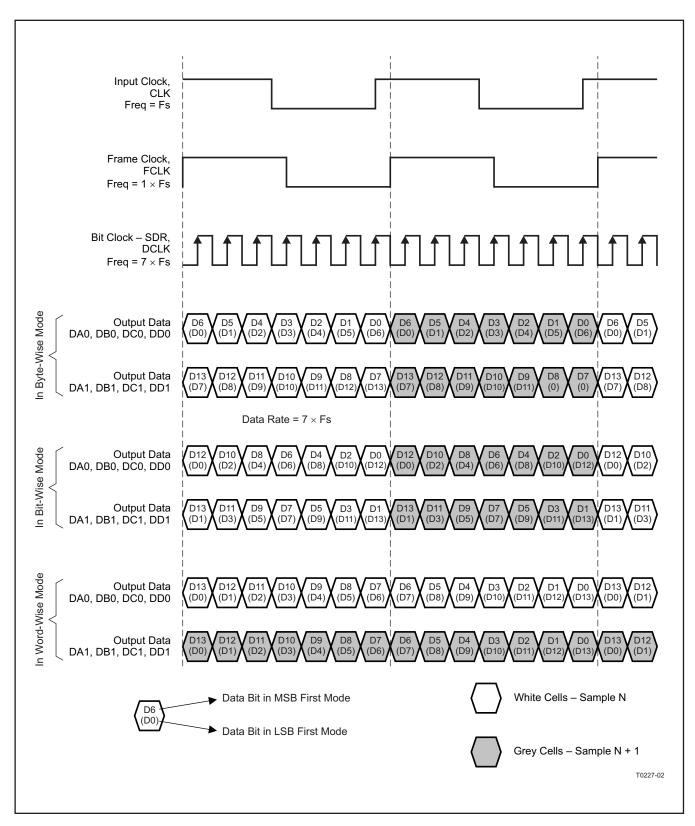
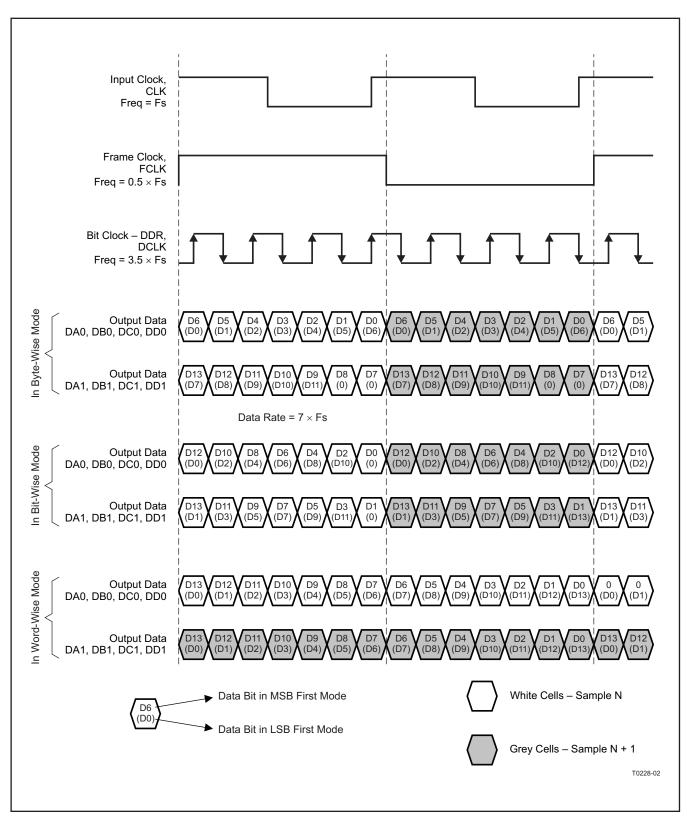


Figure 96. 2-Wire Interface 14× Serialization - SDR Bit Clock





A. In the byte-wise and bit-wise modes, the frame clock frequency is 1 x Fs. In the word-wise mode, the frame clock frequency is 0.5 x Fs

Figure 97. 2-Wire interface 14× Serialization - DDR Bit Clock



#### **OUTPUT BIT ORDER**

In the 2-wire interface, three types of bit order are supported - byte-wise, bit-wise and word-wise.

**Byte-wise:** Each 14-bit sample is split across the 2 wires. Wires DA0 and DB0 carry the 7 LSB bits D6-D0 and wires DA1 and DB1 carry the 7 MSB bits.

**Bit-wise:** Each 14-bit sample is split across the 2 wires. Wires DA0 and DB0 carry the 7 even bits (D0,D2,D4..) and wires DA1 and DB1 carry the 7 odd bits (D1,D3,D5...).

**Word-wise:** In this case, all 14-bits of a sample are sent over a single wire. Successive samples are sent over the 2 wires. For example sample N is sent on wires DA0 and DB0 while sample N+1 is sent over wires DA1 and DB1. The frame clock frequency is 0.5x sampling frequency, with the rising edge aligned with the start of each word.

#### MSB/LSB FIRST

By default after reset, the 14-bit ADC data is output serially with the MSB first (D13, D12, D11,...D1,D0). The data can be output LSB first also by programming the register bit **<MSB\_LSB\_First>**. In the 2-wire mode, the bit order in each wire is flipped in the LSB first mode.

#### **OUTPUT DATA FORMATS**

Two output data formats are supported – 2s complement (default after reset) and offset binary. They can be selected using the serial interface register bit **<DF>**. In the event of an input voltage overdrive, the digital outputs go to the appropriate full-scale level. For a positive overdrive, the output code is 0x3FFF in offset binary output format, and 0x1FFF in 2s complement output format. For a negative input overdrive, the output code is 0x0000 in offset binary output format and 0x2000 in 2s complement output format.

#### LVDS CURRENT CONTROL

The default LVDS buffer current is 3.5 mA. With an external  $100-\Omega$  termination resistance, this develops  $\pm 350$ -mV logic levels at the receiver. The LVDS buffer currents can also be programmed to 2.5 mA, 3.0 mA and 4.5 mA using the register bits **<LVDS CURR>**. In addition, there exists a current double mode, where the LVDS nominal current is doubled (register bits **<CURR DOUBLE>**, Table 20).

#### LVDS INTERNAL TERMINATION

An internal termination option is available (using the serial interface), by which the LVDS buffers are differentially terminated inside the device. Five termination resistances are available – 166, 200, 250, 333, and 500  $\Omega$  (nominal with ±20% variation). Any combination of these terminations can be programmed; the effective termination will be the parallel combination of the selected resistances. The terminations can be programmed separately for the clock and data buffers (bits **<TERM CLK>** and **<TERM DATA>**, Table 21).

The internal termination helps to absorb any reflections from the receiver end, improving the signal integrity. This makes it possible to drive up to 10 pF of load capacitance, compared to only 5 pF without the internal termination. Figure 98 and Figure 99 show the eye diagram with 5 pF and 10 pF load capacitors (connected from each output pin to ground).

With  $100-\Omega$  internal and  $100-\Omega$  external termination, the voltage swing at the receiver end will be halved (compared to no internal termination). The voltage swing can be restored by using the LVDS current double mode (bits **<CURR DOUBLE>**, Table 20).



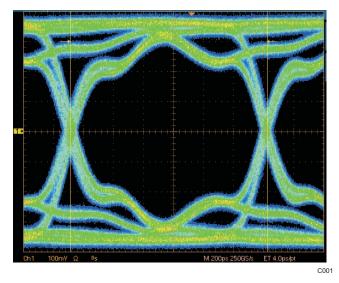


Figure 98. LVDS Data Eye Diagram with 5-pF Load Capacitance (No Internal Termination)

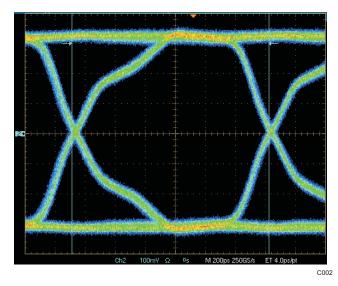


Figure 99. LVDS Data Eye Diagram with 10-pF Load Capacitance (100 Ω Internal Termination)



#### **CAPTURE TEST PATTERNS**

ADS624X outputs the bit clock (DCLK), positioned nearly at the center of the data transitions. It is recommended to route the bit clock, frame clock and output data lines with minimum relative skew on the PCB. This ensures sufficient setup/hold times for a reliable capture by the receiver.

The DESKEW is a 1010... or 0101... pattern output on the serial data lines that can be used to verify if the receiver capture clock edge is positioned correctly. This may be useful in case there is some skew between DCLK and serial data inside the receiver. Once deserialized, it is required to ensure that the parallel data is aligned to the frame boundary. The SYNC test pattern can be used for this. For example, in the 1-wire interface, the SYNC pattern is 7 '1's followed by 7 '0's (from MSB to LSB). This information can be used by the receiver logic to shift the deserialized data till it matches the SYNC pattern.

In addition to DESKEW and SYNC, the ADS624X includes other test patterns to verify correctness of the capture by the receiver such as all zeros, all ones and toggle. These patterns are output on all four channel data lines simultaneously. Some patterns like custom and sync are affected by the type of interface selected, serialization and bit order.

Table 26. Test Patterns

PATTERN	DESCRIPTION
All zeros	Outputs logic low.
All ones	Outputs logic high.
Toggle	Outputs toggle pattern - <d13-d0> alternates between 10101010101010 and 01010101010101 every clock cycle.</d13-d0>
Custom	Outputs a 14-bit custom pattern. The 14-bit custom pattern can be specified into two serial interface registers. In the 2-wire interface, each code is sent over the 2 wires depending on the serialization and bit order.
Sync	Outputs a sync pattern.
Deskew	Outputs deskew pattern. Either <d13-d0> = 1010101010101010 OR <d11-d0> = 010101010101010 every clock cycle.</d11-d0></d13-d0>

Table 27. SYNC Pattern

INTERFACE OPTION	SERIALIZATION	SYNC PATTERN ON EACH WIRE
4 \\//iro	14 X	MSB-11111110000000-LSB
1-Wire	16 X	MSB-111111111000000000-LSB
2-Wire	14 X	MSB-1111000-LSB
∠-vvire	16 X	MSB-11110000-LSB



#### **OUTPUT TIMINGS AT LOWER SAMPLING FREQUENCIES**

Setup, hold and other timing parameters are specified across sampling frequencies and for each type of output interface in the tables below.

Table 29 to Table 32: Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = LVDD = 3.3 V,  $C_L = 5$  pF,  $I_O = 3.5$  mA,  $R_L = 100$   $\Omega$ , no internal termination, unless otherwise noted.

Timing parameters are ensured by design and characterization and not tested in production.

Ts = 1/ Sampling frequency = 1/Fs

Table 28. Clock Propagation Delay for different interface options

INTERFACE	SERIALIZATION	CLOCK PROPAGATION DELAY, t <sub>pd_clk</sub>	SERIALIZER LATENCY (1) clock cycles
4 wine with DDD hit aleals	14x	$t_{pd\_clk} = 0.428xT_s + t_{delay}$	0
1-wire with DDR bit clock	16x	$t_{pd\_clk} = 0.375xT_s + t_{delay}$	0
2-wire with DDR bit clock	14x	$t_{pd\_clk} = 0.857xT_s + t_{delay}$	$2 \\ (\text{when } t_{pd\_clk} \ge T_s)$ $1 \\ (\text{when } t_{pd\_clk} < T_s)$
2-wire with SDR bit clock		$t_{pd\_clk} = 0.428xT_s + t_{delay}$	0
2-wire with DDR bit clock	16x	$t_{pd\_clk} = 0.75xT_s + t_{delay}$	$ \begin{array}{c} 1 \\ \text{(when } t_{pd\_clk} \geq T_s) \\ 0 \\ \text{(when } t_{pd\_clk} < T_s) \end{array} $
2-wire with SDR bit clock		$t_{pd\_clk} = 0.375xT_s + t_{delay}$	0

<sup>(1)</sup> Note that the total latency = ADC latency + internal serializer latency. The ADC latency is 12 clock cycles.

## Table 29. Timings for 1-Wire Interface

SERIALIZATION	SAMPLING FREQUENCY	DATA SETUP TIME, t <sub>su</sub> ns			DATA HOLD TIME, t <sub>h</sub>			t <sub>delay</sub> ns		
	MSPS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX
	65	0.3	0.5		0.4	0.6			F <sub>s</sub> ≥ 40 MSPS	
4.4.	40	0.65	0.85		0.7	0.9		3	4	5
14×	20	1.3	1.65		1.6	1.9			F <sub>s</sub> < 40 MSPS	
	10	3.2	3.5		3.2	3.6		3	4.5	6
									F <sub>s</sub> ≥ 40 MSPS	
40	<b>6</b> 5	0.00	0.42		0.35	0.55		3	4	5
16×	65	0.22							F <sub>s</sub> < 40 MSPS	
									3	4.5

Submit Documentation Feedback



## Table 30. Timings for 2-Wire Interface, DDR Bit Clock

SERIALIZATION	SAMPLING FREQUENCY	DATA SETUP TIME, t <sub>su</sub> ns			DATA HOLD TIME, t <sub>h</sub>			t <sub>delay</sub> ns		
	MSPS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX
	105	0.45	0.65		0.5	0.7			F <sub>s</sub> ≥ 45 MSPS	
	92	0.55	0.75		0.6	0.8		3.4		5.4
14×	80	0.65	0.85		0.7	0.9		3.4	4.4	5.4
	65	0.8	1.1		0.8	1.1			F <sub>s</sub> < 45 MSPS	
	40	1.4	1.7		1.5	1.9		3.7	5.2	6.7
	105	0.35	0.55		0.4	0.6			F <sub>s</sub> ≥ 45 MSPS	
	92	0.45	0.65		0.5	0.7		0.4	4.4	
16×	80	0.55	0.75		0.6	0.8		3.4	4.4	5.4
	65	0.6	0.9		0.7	1		F <sub>s</sub> < 45 MSPS		•
	40	1.1	1.4		1.3	1.7		3.7	5.2	6.7

## Table 31. Timings for 2-Wire Interface, SDR Bit Clock

SERIALIZATION	SAMPLING FREQUENCY	DATA SETUP TIME, t <sub>su</sub> ns			DATA HOLD TIME, t <sub>h</sub>			t <sub>delay</sub> ns			
	MSPS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
	65	0.8	1		1	1.2			F <sub>s</sub> ≥ 40 MSPS	•	
14×	40	1.5	1.7		1.6	1.8		3.4	4.4	5.4	
14X	20	3.4	3.6		3.3	3.5			F <sub>s</sub> < 40 MSPS		
	10	6.9	7.2		6.6	6.9		3.7	5.2	6.7	
	65	0.65	0.85		0.8	1.0			F <sub>s</sub> ≥ 40 MSPS		
40	40	1.3	1.5		1.4	1.6		3.4	4.4	5.4	
16×	20	2.8	3.0		2.8	3.0			F <sub>s</sub> < 40 MSPS		
	10	6.0	6.3		5.8	6.1		3.7	5.2	6.7	

## Table 32. Output Jitter (applies to all interface options)

SAMPLING FREQUENCY MSPS	BIT CLC	OCK JITTER, CY ps, peak-pea		FRAME CLOCK JITTER, CYCLE-CYCLE ps, peak-peak			
WISPS	MIN	TYP	MAX	MIN	TYP	MAX	
≥ 65		350			75		



#### **BOARD DESIGN CONSIDERATIONS**

#### Grounding

A single ground plane is sufficient to give optimum performance, provided the analog, digital and clock sections of the board are cleanly partitioned. Refer to the EVM User Guide (SLAU196) for more layout details.

#### **Supply Decoupling**

As the ADS624X already includes internal decoupling, minimal external decoupling can be used without loss in performance. Note that the decoupling capacitors can help to filter external power supply noise, so the optimum number of decoupling capacitors would depend on actual application.

It is recommended to use separate supplies for the analog and digital supply pins to isolate digital switching noise from sensitive analog circuitry. In case only a single 3.3V supply is available, it should be routed first to AVDD. It can then be tapped and isolated with a ferrite bead (or inductor) with decoupling capacitor, before being routed to LVDD.

#### **Exposed Thermal Pad**

For best thermal performance, it is necessary to solder the exposed pad at the bottom of the package to a ground plane using multiple vias. For detailed information, see application notes **QFN Layout Guidelines** (SLOA122A) and **QFN/SON PCB Attachment** (SLUA271A).



#### **DEFINITION OF SPECIFICATIONS**

**Analog Bandwidth** – The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low frequency value.

**Aperture Delay** – The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs.

Aperture Uncertainty (Jitter) - The sample-to-sample variation in aperture delay.

**Clock Pulse Width/Duty Cycle** – The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse width) to the period of the clock signal. Duty cycle is typically expressed as a percentage. A perfect differential sine-wave clock results in a 50% duty cycle.

**Maximum Conversion Rate** – The maximum sampling rate at which certified operation is given. All parametric testing is performed at this sampling rate unless otherwise noted.

Minimum Conversion Rate - The minimum sampling rate at which the ADC functions.

**Differential Nonlinearity (DNL)** – An ideal ADC exhibits code transitions at analog input values spaced exactly 1 LSB apart. The DNL is the deviation of any single step from this ideal value, measured in units of LSBs.

**Integral Nonlinearity (INL)** – The INL is the deviation of the ADC's transfer function from a best fit line determined by a least squares curve fit of that transfer function, measured in units of LSBs.

**Gain Error** – The gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range.

**Offset Error** – The offset error is the difference, given in number of LSBs, between the ADC's actual average idle channel output code and the ideal average idle channel output code. This quantity is often mapped into mV.

**Temperature Drift** – The temperature drift coefficient (with respect to gain error and offset error) specifies the change per degree Celsius of the parameter from  $T_{MIN}$  to  $T_{MAX}$ . It is calculated by dividing the maximum deviation of the parameter across the  $T_{MIN}$  to  $T_{MAX}$  range by the difference  $T_{MAX}$ – $T_{MIN}$ .

**Signal-to-Noise Ratio** – SNR is the ratio of the power of the fundamental (PS) to the noise floor power (PN), excluding the power at DC and the first nine harmonics.

$$SNR = 10Log10 \frac{P_S}{P_N}$$
 (3)

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

**Signal-to-Noise and Distortion (SINAD)** – SINAD is the ratio of the power of the fundamental ( $P_S$ ) to the power of all the other spectral components including noise ( $P_N$ ) and distortion ( $P_D$ ), but excluding dc.

$$SINAD = 10Log10 \frac{P_S}{PN + PD}$$
(4)

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

**Effective Number of Bits (ENOB)** – The ENOB is a measure of a converter's performance as compared to the theoretical limit based on quantization noise.

$$ENOB = \frac{SINAD - 1.76}{6.02} \tag{5}$$

**Total Harmonic Distortion (THD)** – THD is the ratio of the power of the fundamental (P<sub>S</sub>) to the power of the first nine harmonics (PD).

$$THD = 10Log10 \frac{P_S}{PD}$$
 (6)

THD is typically given in units of dBc (dB to carrier).



**Spurious-Free Dynamic Range (SFDR)** – The ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier).

**Two-Tone Intermodulation Distortion** – IMD3 is the ratio of the power of the fundamental (at frequencies f1 and f2) to the power of the worst spectral component at either frequency 2f1–f2 or 2f2–f1. IMD3 is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

**DC Power Supply Rejection Ratio (DC PSRR)** – The DC PSSR is the ratio of the change in offset error to a change in analog supply voltage. The DC PSRR is typically given in units of mV/V.

AC Power Supply Rejection Ratio (AC PSRR) – AC PSRR is the measure of rejection of variations in the supply voltage by the ADC. If  $\Delta$ Vsup is the change in supply voltage and  $\Delta$ Vout is the resultant change of the ADC output code (referred to the input), then

$$PSRR = 20Log10 \frac{\Delta Vout}{\Delta Vsup}, \text{ expressed in dBc}$$
 (7)

**Voltage Overload Recovery** – The number of clock cycles taken to recover to less than 1% error after an overload on the analog inputs. This is tested by separately applying a sine wave signal with 6dB positive and negative overload. The deviation of the first few samples after the overload (from their expected values) is noted.

**Common Mode Rejection Ratio (CMRR)** – CMRR is the measure of rejection of variations in the analog input common-mode by the ADC. If  $\Delta$ Vcm\_in is the change in the common-mode voltage of the input pins and  $\Delta$ Vout is the resultant change of the ADC output code (referred to the input), then

CMRR = 
$$20\text{Log}10\frac{\Delta V \text{out}}{\Delta V \text{cm\_in}}$$
, expressed in dBc (8)

Cross-Talk (only for multi-channel ADC) – This is a measure of the internal coupling of a signal from adjacent channel into the channel of interest. It is specified separately for coupling from the immediate neighbouring channel (near-channel) and for coupling from channel across the package (far-channel). It is usually measured by applying a full-scale signal in the adjacent channel. Cross-talk is the ratio of the power of the coupling signal (as measured at the output of the channel of interest) to the power of the signal applied at the adjacent channel input. It is typically expressed in dBc.





## **REVISION HISTORY**

Cł	hanges from Revision A (July 2007) to Revision B	Page
•	Added Frame setup time and Frame hold time to the TIMING SPECIFICATIONS table	9
•	Changed Figure 2	12
•	Changed text in the USING PARALLEL INTERFACE CONTROL ONLY section From: "The parallel pins can be configured using a simple resistor string" To: "The parallel pins can be configured using a simple resistor string (with 10% tolerance resistors)"	
	Changed Figure 3	
•	Changed Table 9	15
•	Changed Table 10	15
•	Changed Table 12	15
•	Added Note 3 to Table 13	18
•	Added note to the DESCRIPTION OF SERIAL REGISTERS - "After a hardware or software reset, all register bits are cleared to '0'"	19
•	Added 32K point FFT to TYPICAL CHARACTERISTICS test conditions	28
•	Added Gain 5 setting to CLOCK BUFFER GAIN section	
•	Added Note A to Figure 97	58





26-Oct-2016

#### PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
ADS6242IRGZT	ACTIVE	VQFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ6242	Samples
ADS6243IRGZT	ACTIVE	VQFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ6243	Samples
ADS6244IRGZR	ACTIVE	VQFN	RGZ	48	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ6244	Samples
ADS6244IRGZT	ACTIVE	VQFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ6244	Samples
ADS6245IRGZR	ACTIVE	VQFN	RGZ	48	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ6245	Samples
ADS6245IRGZT	ACTIVE	VQFN	RGZ	48	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	AZ6245	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free** (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between

the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.



## **PACKAGE OPTION ADDENDUM**

26-Oct-2016

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**PACKAGE MATERIALS INFORMATION** 

www.ti.com 18-Aug-2014

## TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

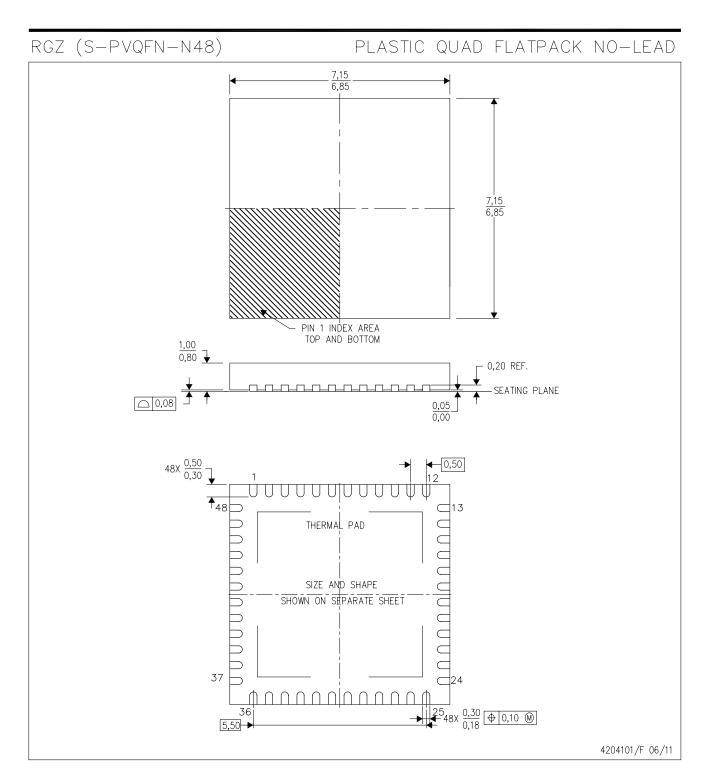
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS6242IRGZT	VQFN	RGZ	48	250	180.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS6243IRGZT	VQFN	RGZ	48	250	180.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS6244IRGZR	VQFN	RGZ	48	2500	330.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS6244IRGZT	VQFN	RGZ	48	250	180.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS6245IRGZR	VQFN	RGZ	48	2500	330.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2
ADS6245IRGZT	VQFN	RGZ	48	250	180.0	16.4	7.3	7.3	1.5	12.0	16.0	Q2

www.ti.com 18-Aug-2014



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
ADS6242IRGZT	VQFN	RGZ	48	250	213.0	191.0	55.0	
ADS6243IRGZT	VQFN	RGZ	48	250	213.0	191.0	55.0	
ADS6244IRGZR	VQFN	RGZ	48	2500	336.6	336.6	28.6	
ADS6244IRGZT	VQFN	RGZ	48	250	213.0	191.0	55.0	
ADS6245IRGZR	VQFN	RGZ	48	2500	336.6	336.6	28.6	
ADS6245IRGZT	VQFN	RGZ	48	250	213.0	191.0	55.0	



- NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
  - B. This drawing is subject to change without notice.
  - C. Quad Flatpack, No-leads (QFN) package configuration.
  - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
  - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
  - F. Falls within JEDEC MO-220.



## RGZ (S-PVQFN-N48)

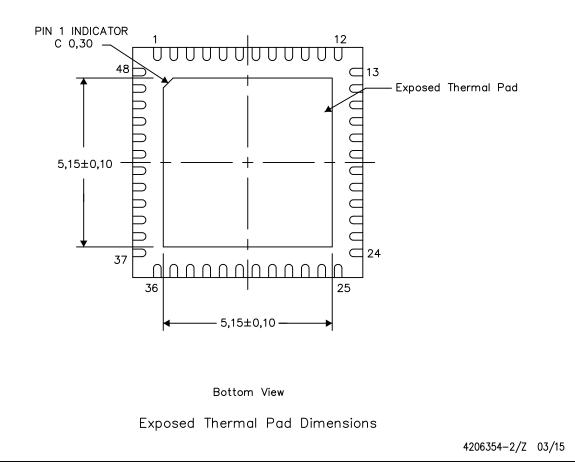
## PLASTIC QUAD FLATPACK NO-LEAD

#### THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No—Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

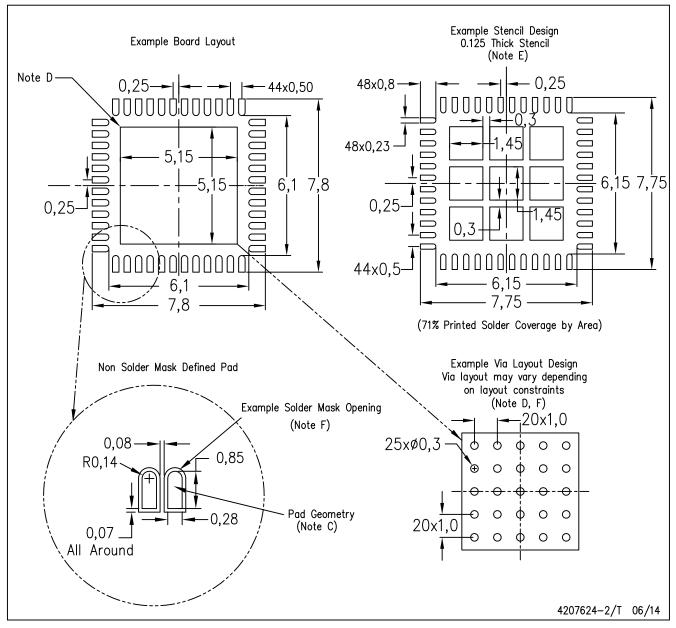


NOTE: All linear dimensions are in millimeters



# RGZ (S-PVQFN-N48)

## PLASTIC QUAD FLATPACK NO-LEAD



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat—Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <a href="http://www.ti.com">http://www.ti.com</a>>.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



#### IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

#### Products Applications

Audio www.ti.com/audio Automotive and Transportation www.ti.com/automotive **Amplifiers** amplifier.ti.com Communications and Telecom www.ti.com/communications **Data Converters** dataconverter.ti.com Computers and Peripherals www.ti.com/computers **DLP® Products** www.dlp.com Consumer Electronics www.ti.com/consumer-apps DSP dsp.ti.com **Energy and Lighting** www.ti.com/energy Clocks and Timers www.ti.com/clocks Industrial www.ti.com/industrial Interface interface.ti.com Medical www.ti.com/medical Logic Security www.ti.com/security logic.ti.com

Power Mgmt power.ti.com Space, Avionics and Defense www.ti.com/space-avionics-defense

Microcontrollers microcontroller.ti.com Video and Imaging www.ti.com/video

RFID www.ti-rfid.com

OMAP Applications Processors www.ti.com/omap TI E2E Community e2e.ti.com

Wireless Connectivity www.ti.com/wirelessconnectivity